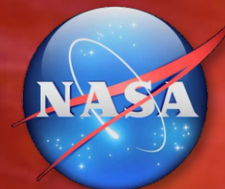
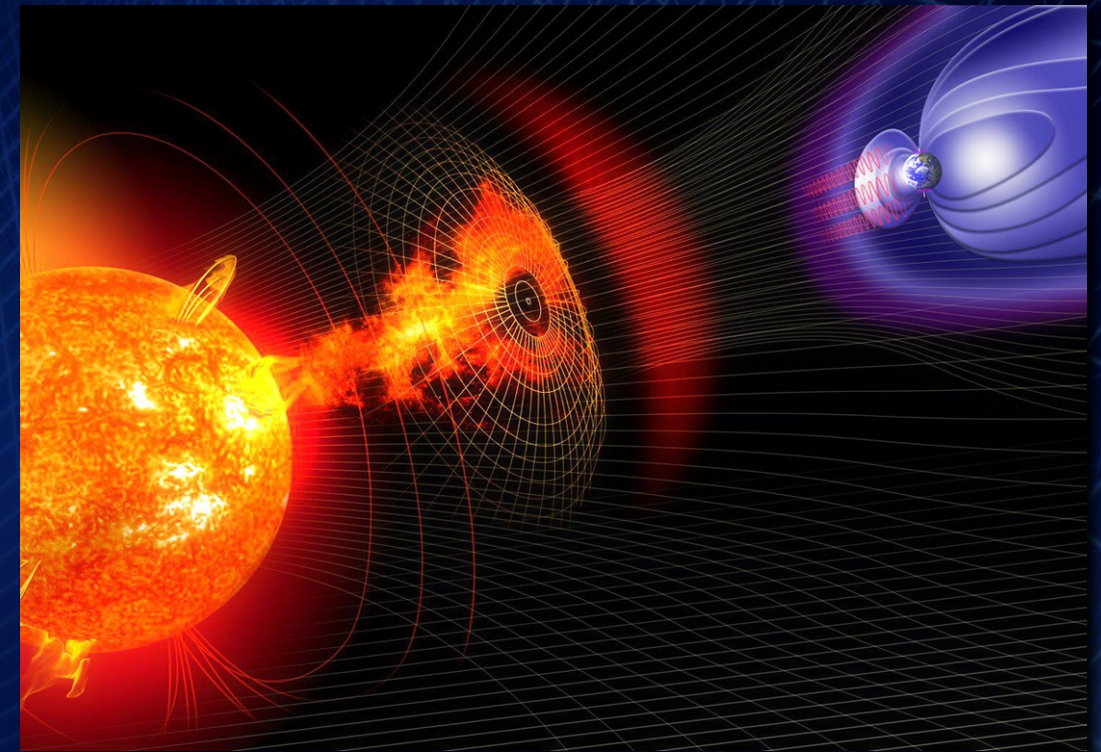


Simulating Solar Storms on GPUs with Fortran Standard Parallelism

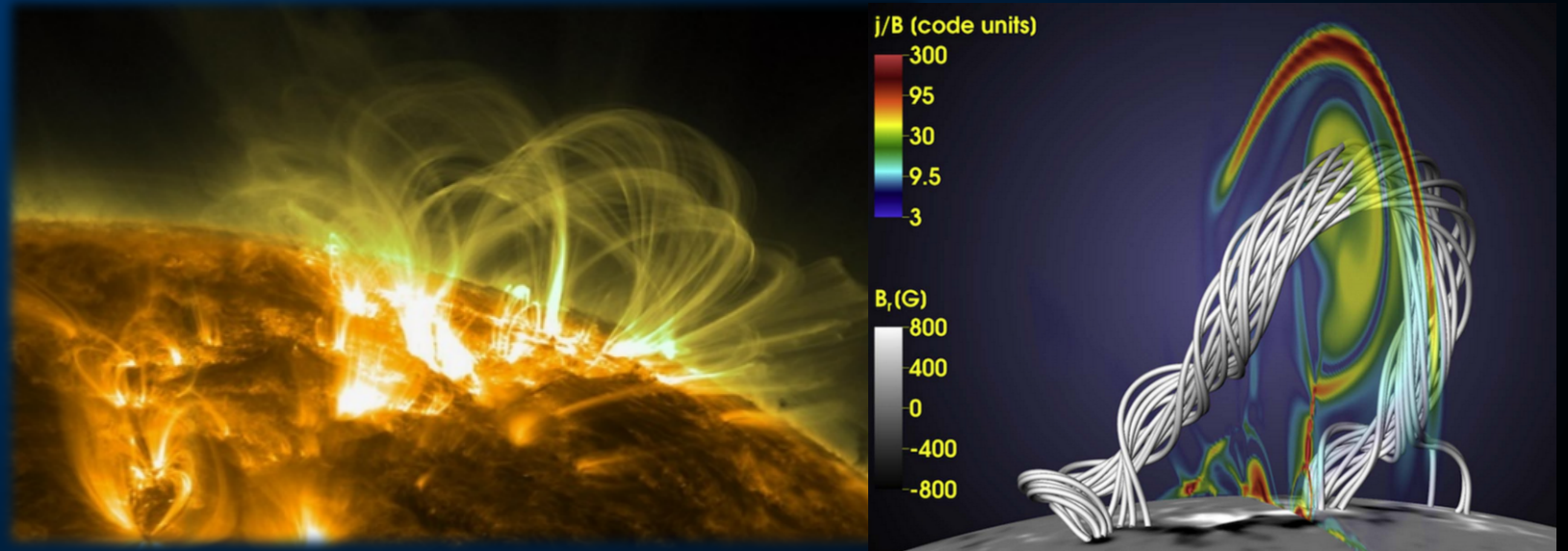
Ronald M. Caplan, Miko M. Stulajter, Jon A. Linker,
Tibor Torok, Cooper Downs, Andres Reyes, Viacheslav S. Titov,
Roberto Lionello, and Pete Riley



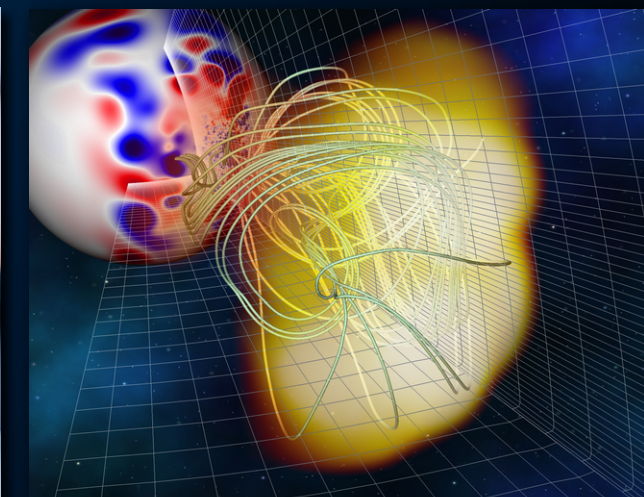
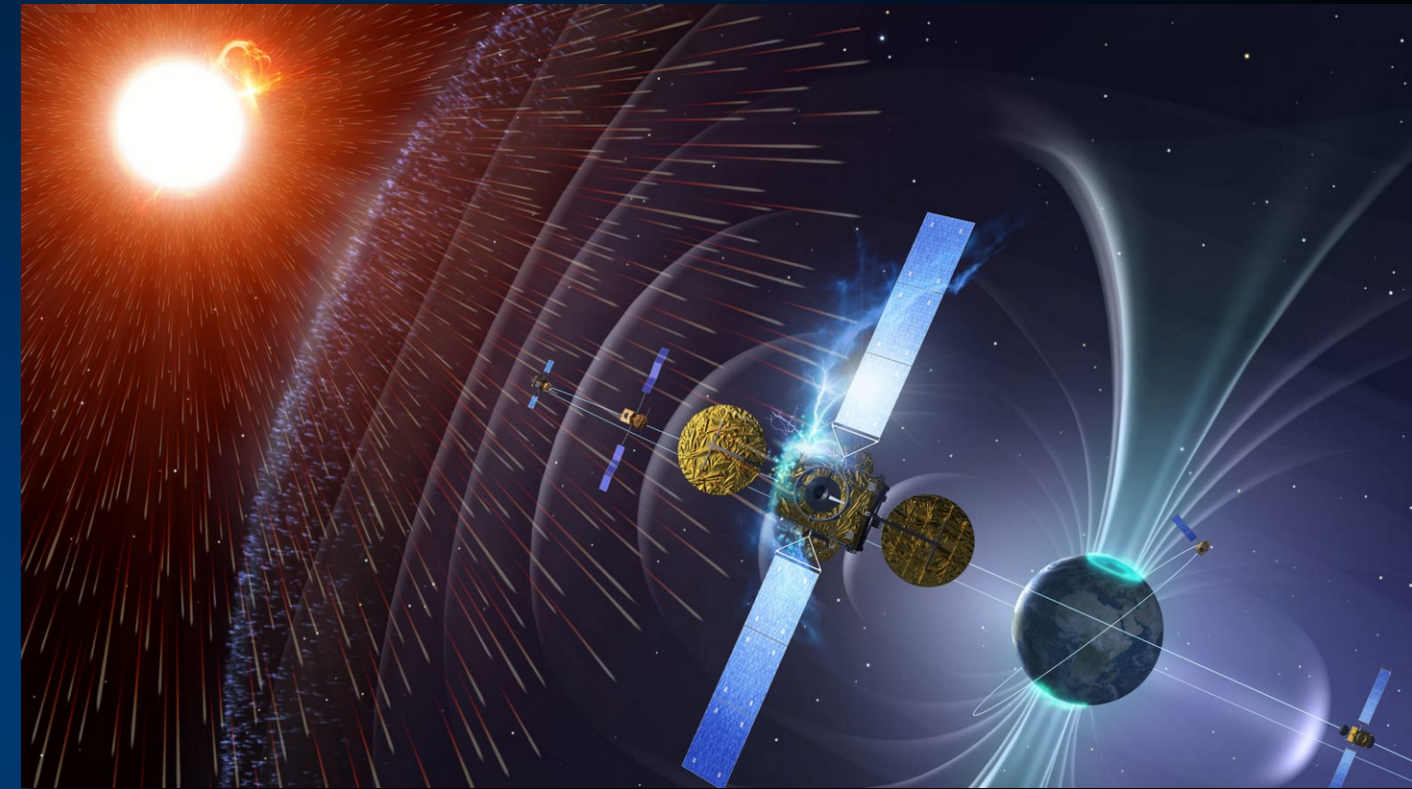
- ① The `what` & `why` of Solar Storms
- ① How *you* can model Solar Storms
- ① Run on GPUs with “just Fortran”?
- ① Let’s see it!



- ⊖ Large explosive events on the Sun such as solar flares and coronal mass ejections (CME)
- ⊖ CMEs can eject billions of tons of magnetized million-degree plasma out into space
- ⊖ They originate in regions of strong magnetic field on the solar surface called “active regions”
- ⊖ Their structure can be mathematically modeled with a twisted “flux rope” magnetic field



- Ⓧ **Interesting!** CMEs involve multiple levels of physical scales and processes
- Ⓧ **Having many observations** allows validation of physical models
- Ⓧ **Important!** CME impacts at Earth can cause interference & damage to our electronic infrastructure including GPS satellites and the power grid
- Ⓧ **Numerical models** are a key tool in solar storm analysis and prediction

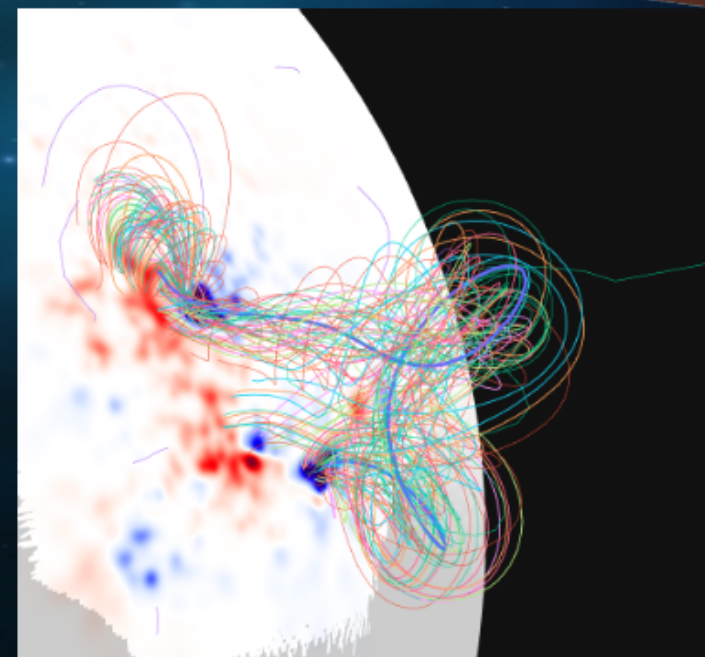


CORHEL-CME *Recipe for Making Solar Storms*

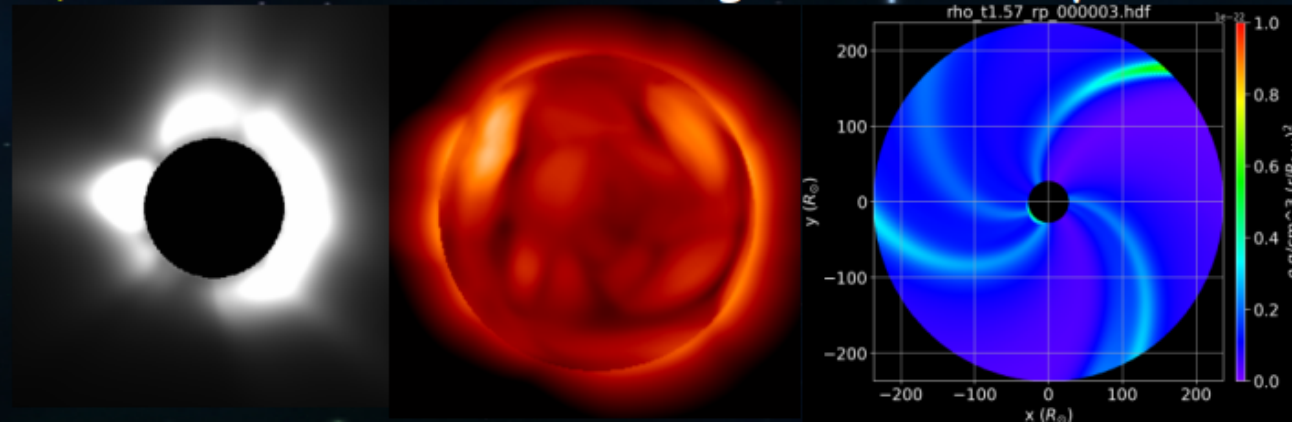
1) Get the Sun's surface magnetic field from satellite observations:



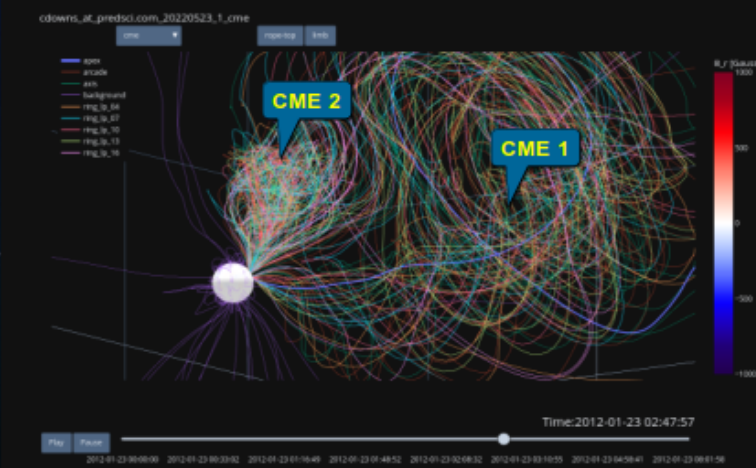
2) Design twisted magnetic rope(s) to erupt:



3) Simulate the Sun's background atmosphere:

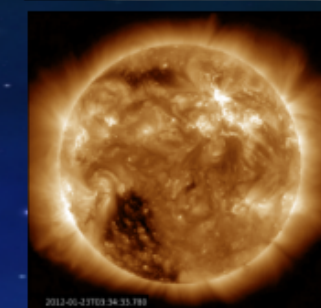
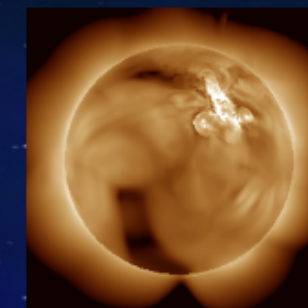
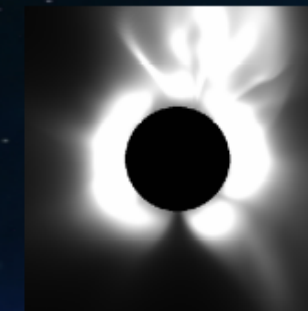


4) Insert the rope(s) and run a simulation to make them erupt and travel to Earth!



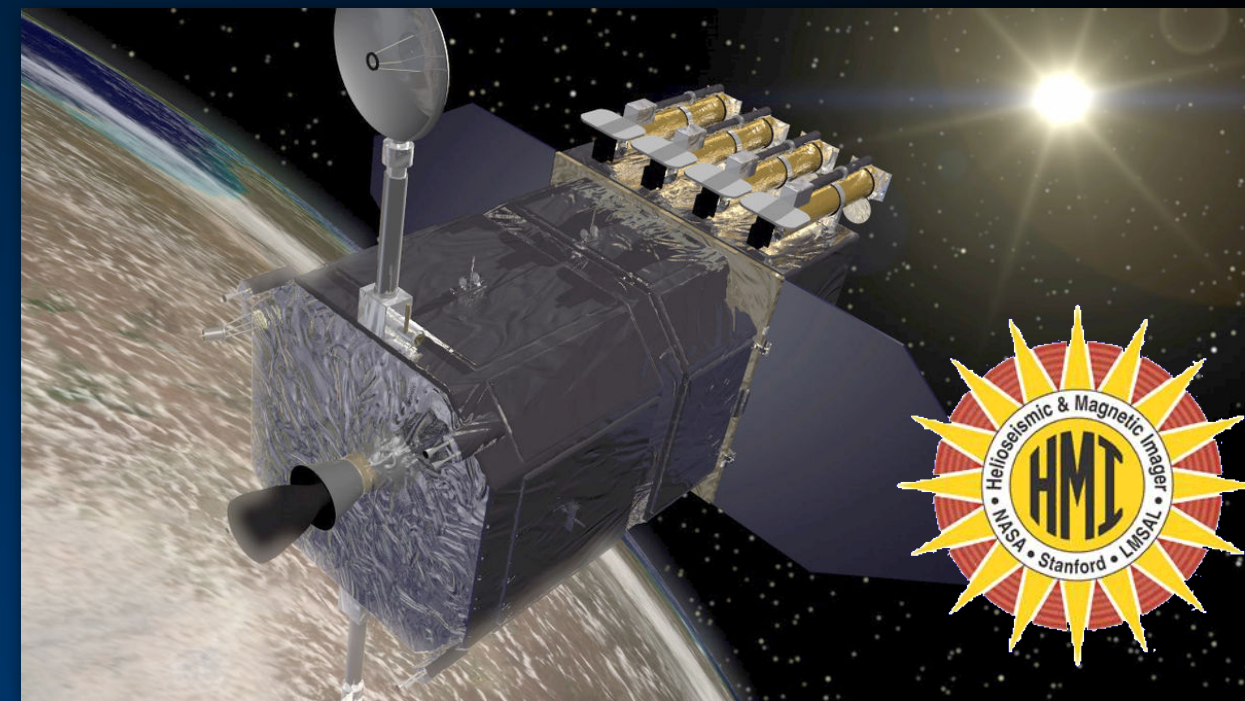
Simulation

Actual Sun



CORHEL-CME

- Ⓧ Grab observations of the solar surface magnetic field
- Ⓧ Most observations along Sun-Earth line, but need full Sun data!
 - “Synoptic”/Diachronic: Take band of data over ~28 day solar rotation (default)
 - Synchronic: Surface flux transport models can simulate the flow of the field behind the Sun
- Ⓧ Automatic processing of full-Sun data including binning, flux balancing, and smoothing



HIPT



github.com/predsci/hipft

DIFFUSE



Stulajter, et. al. Lec Notes in Comp Sci, 13194, 3-21 (2022)

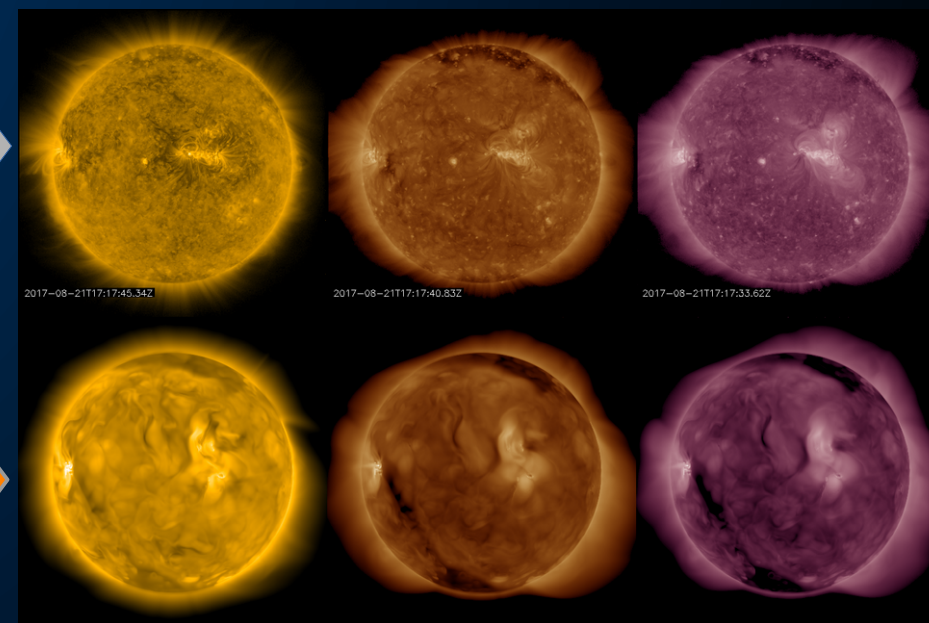
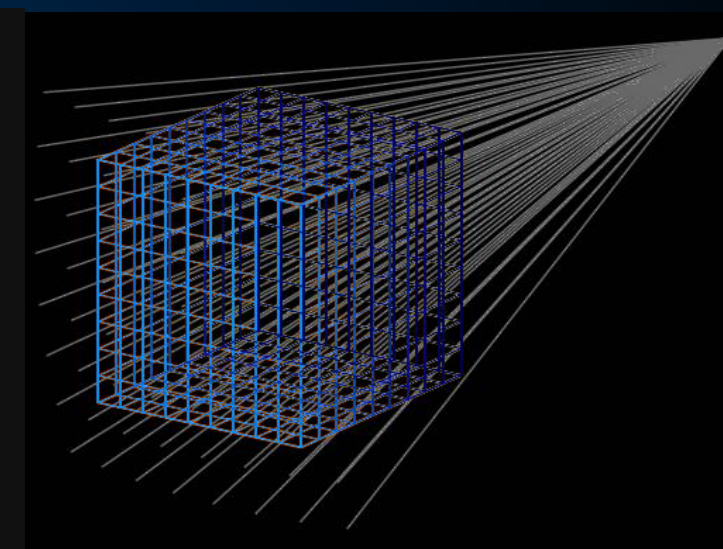
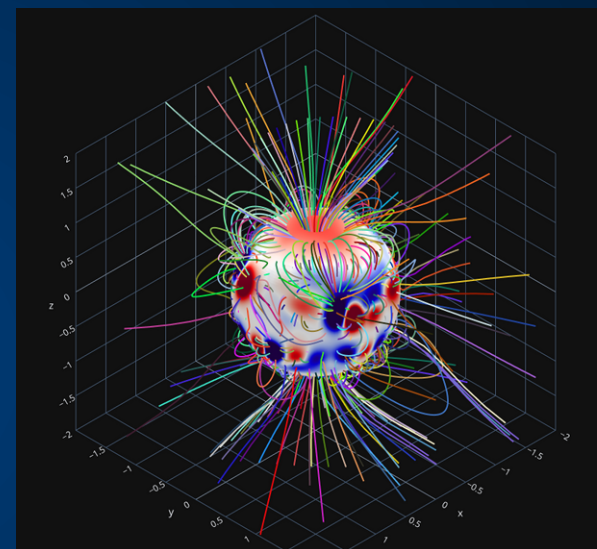
CORHEL-CME

POT3D



github.com/predsci/pot3d

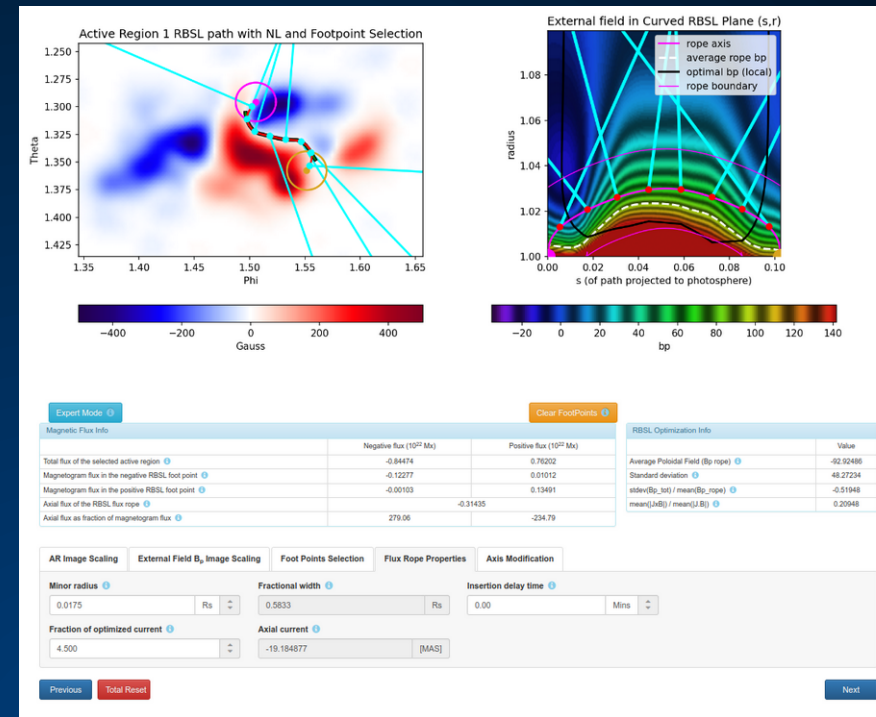
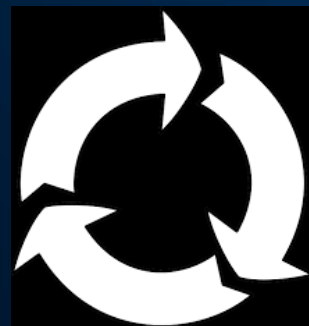
- ① Use surface field as lower boundary condition for a magnetohydrodynamic (MHD) simulation of the Sun's atmosphere
- ① Start with a "potential field" solve for the initial 3D magnetic field (similar to POT3D)
- ① Run the MHD simulation long enough to reach a quasi-steady background solution
- ① Trace through solution (with a physics model) to create synthetic observations directly comparable to real ones



MAS →

CORHEL-CME

- Design flux rope(s) with GUI
- Step-by-step guides through tool-tips and tutorial videos
- Test if flux rope(s) are eruptive with reduced-model MHD simulation (quick ~20 minute turnaround time on 4xGPUs)
- Refine rope(s) parameters and repeat!



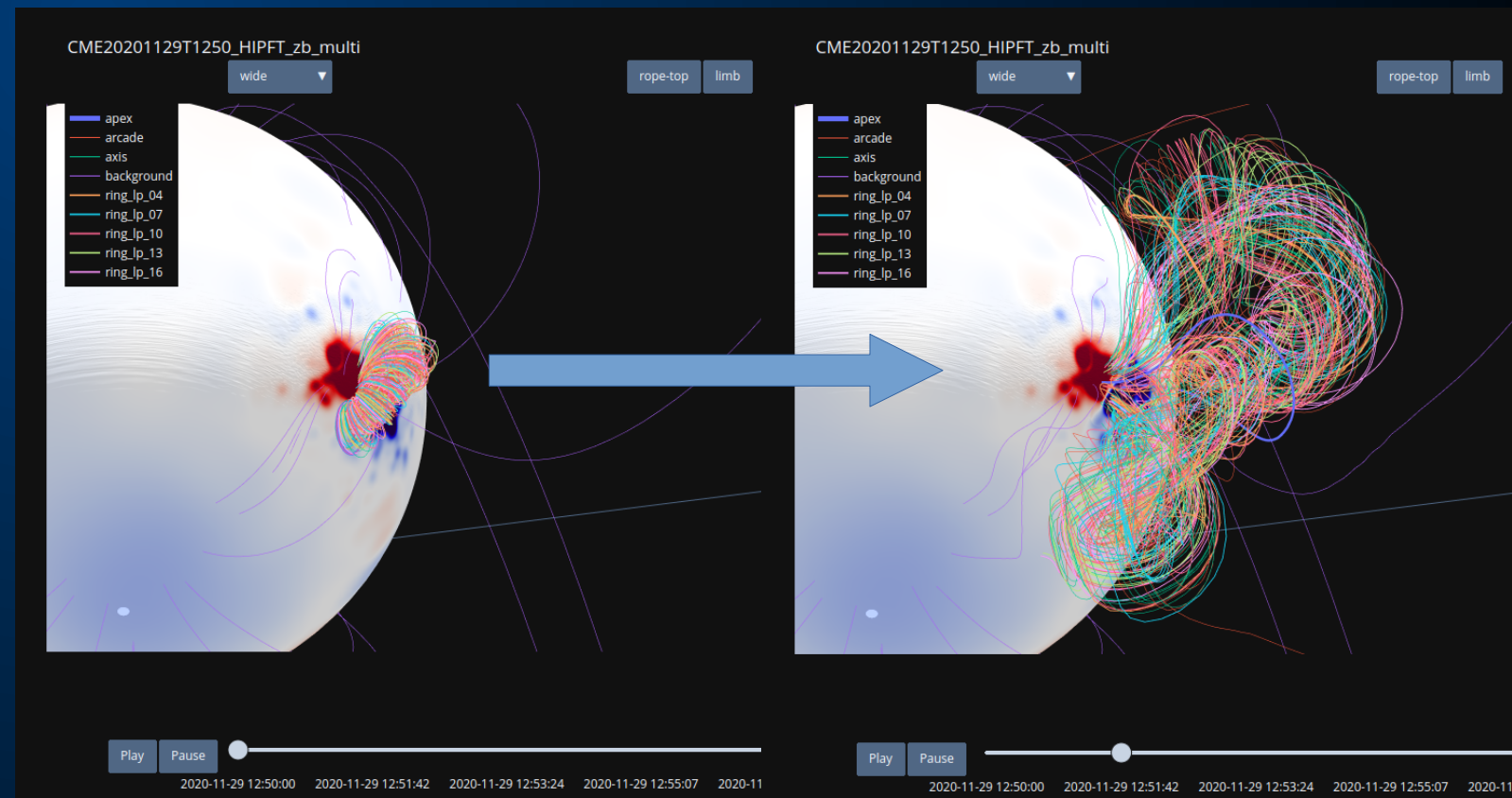
Magnetic Flux Info

This table shows the axial magnetic flux of the RBSL flux rope and of the background active region (AR). Use this information to optimize the flux-rope parameters and foot-point locations. The total rope flux should not exceed the total AR flux significantly. The last row compares the rope flux with the AR flux within the foot points. Values larger than 100% indicate that the flux of the rope is larger than the AR flux.

	Negative Flux (10^{22} Mx)	Positive Flux (10^{22} Mx)
Total flux of the selected active region	-1.54699	1.40302
Magnetogram flux in the negative RBSL foot point	-0.00205	0.00270
Magnetogram flux in the positive RBSL foot point	0.00000	0.54007
Axial flux of the RBSL flux rope		-0.31586
Axial flux as fraction of magnetogram flux	-1000.00	701.06

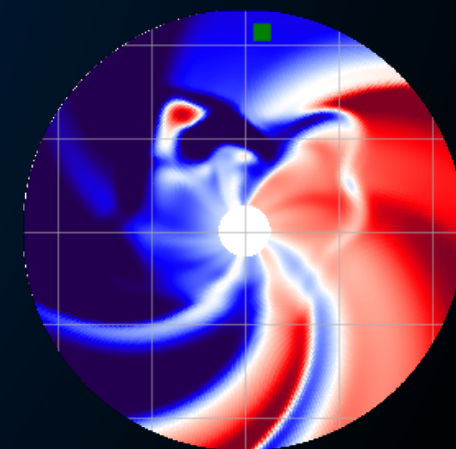
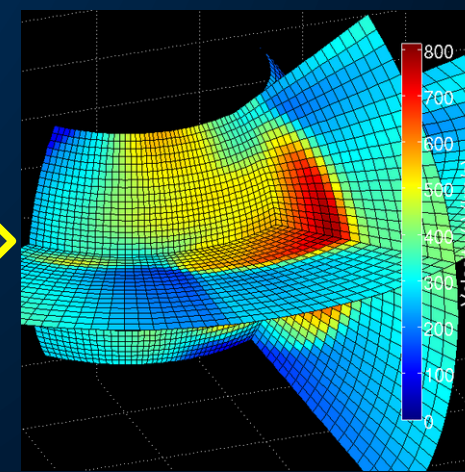
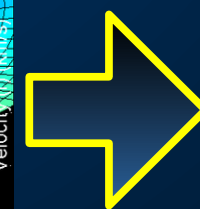
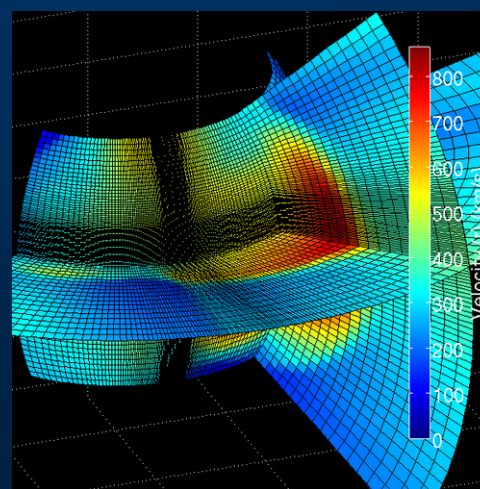
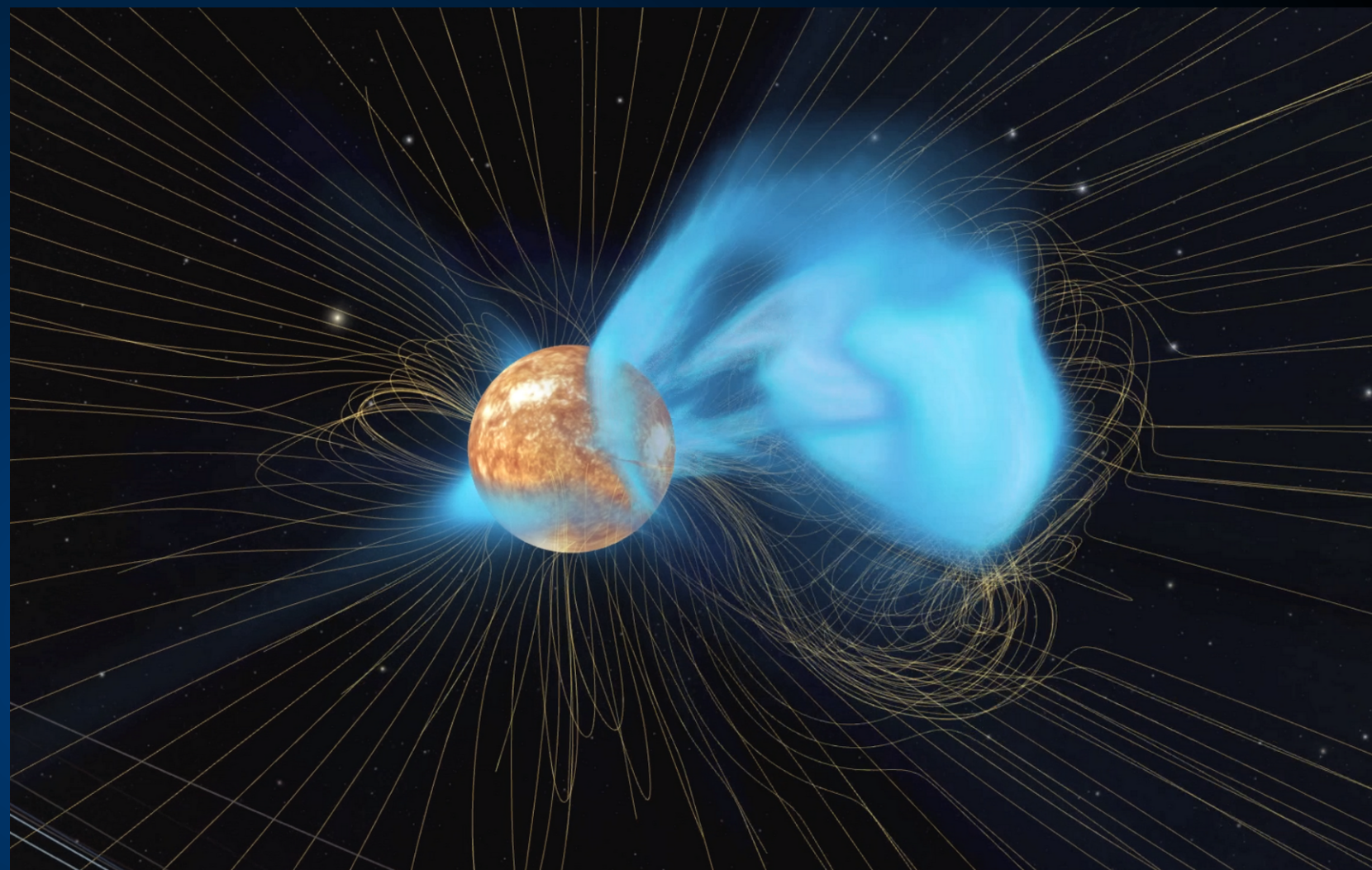
Source Region Selection

Select a CME source region. Specify an active region (AR) by clicking and dragging the cursor on the magnetogram map or by entering the position of the top-left and bottom-right corners of the rectangle in the AR Selection box. In general, a smaller rectangle will result in a smaller current sheet and a smaller CME. The AR flux will be calculated according to whether you use CMEs with the available magnetogram data. The "AR Flux" will be calculated using the "AR Flux" data. The "AR Flux" will be calculated using the "AR Flux" data. The "AR Flux" will be calculated using the "AR Flux" data.



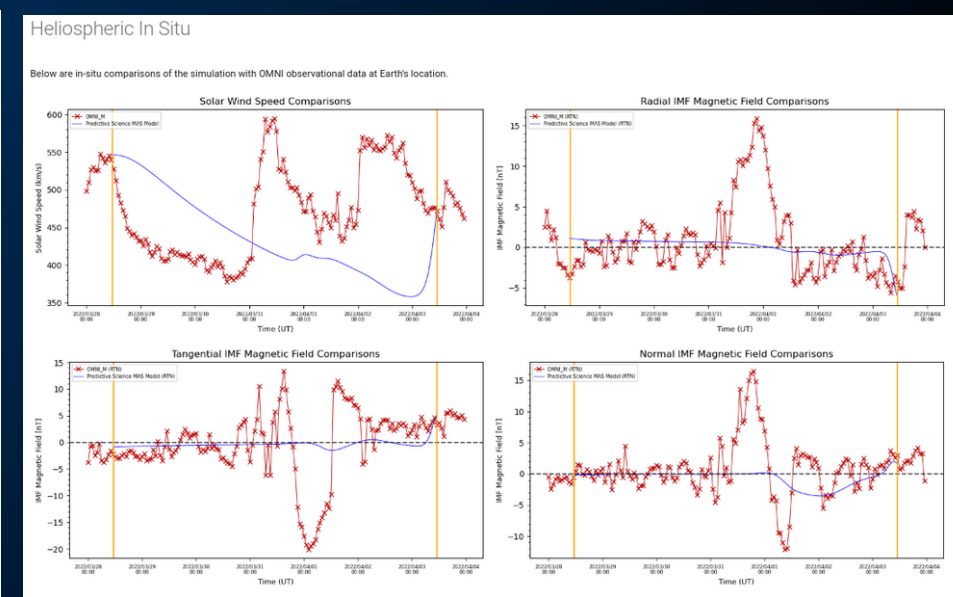
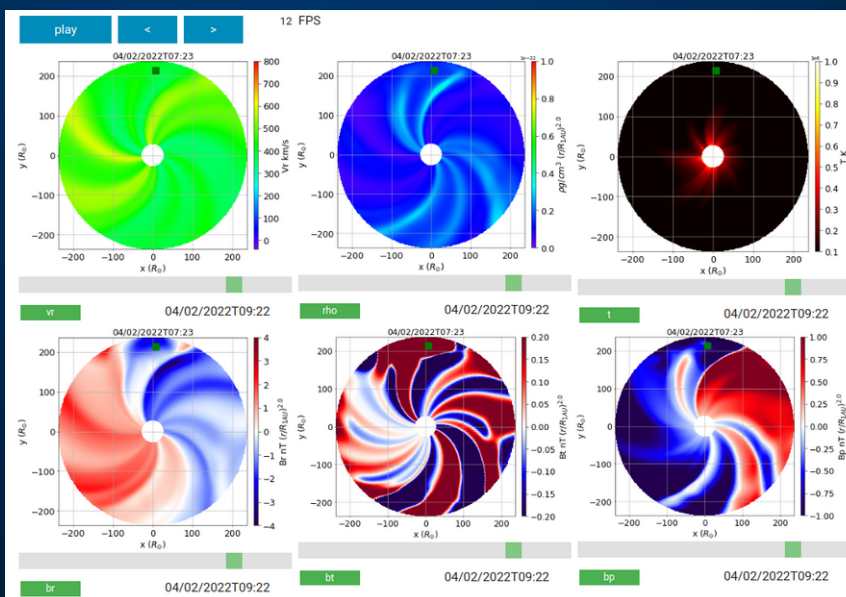
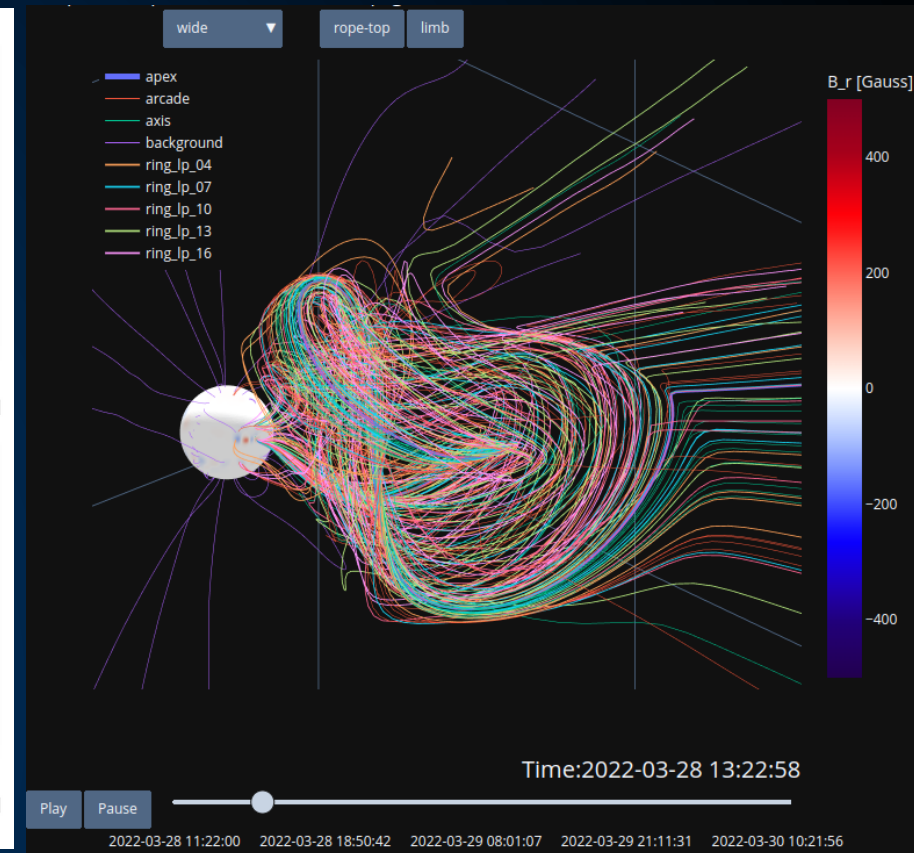
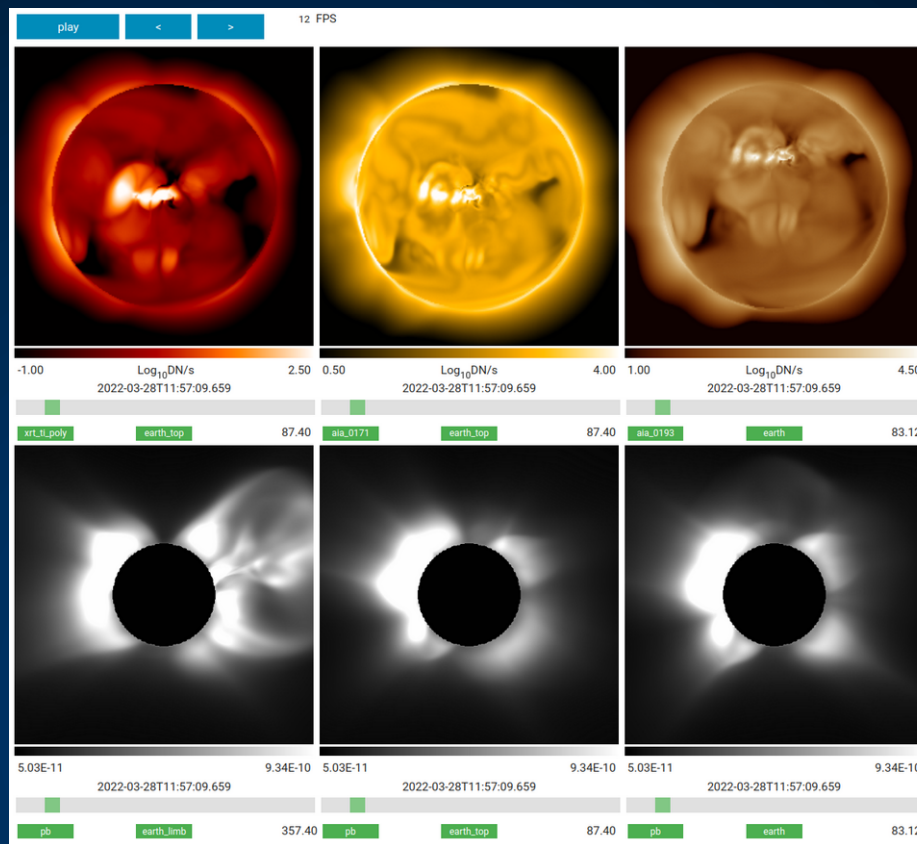
CORHEL-CME

- ① Use MHD background solution as initial condition
- ② Insert flux rope(s)
- ③ Run full MHD CME simulation from Sun to Earth
- ④ Re-mesh after initial eruption to reduce compute time



CORHEL-CME

- Auto-generated reports to analyze CME
- Simulation can be used as input to other models such as the STAT solar energetic particle model



CORHEL-CME

- Ⓧ Web GUI hosted at NASA's CCMC
- Ⓧ Simulations are run on a **single** AWS GPU instance
- Ⓧ Computationally expensive MHD simulations run using the MAS code

MAS



ccmc.gsfc.nasa.gov

ccmc.gsfc.nasa.gov/models/CORHEL-CME~1

NASA + AWS + NVIDIA V100 TENSOR CORE GPU

EC2 P3 8xV100

MAS

MAGNETOHYDRODYNAMIC ALGORITHM OUTSIDE A SPHERE



$$\frac{\partial \mathbf{A}}{\partial t} = \mathbf{v} \times (\nabla \times \mathbf{A}) - \frac{c^2 \eta}{4\pi} \nabla \times \nabla \times \mathbf{A}$$

RESISTIVITY

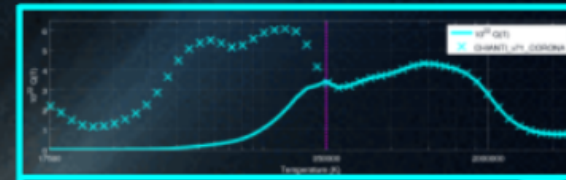
$$\frac{\partial \rho}{\partial t} = -\nabla \cdot (\rho \mathbf{v})$$

$$\frac{\partial T}{\partial t} = -\nabla \cdot (T \mathbf{v}) - (\gamma - 2) (T \nabla \cdot \mathbf{v}) + \frac{\gamma - 1}{2} \frac{m_p}{k} \rho \left[-\nabla \cdot (\mathbf{q}_1 + \mathbf{q}_2) - \frac{\rho^2}{m_p^2} Q(T) + H \right]$$

THERMAL CONDUCTION

$$\mathbf{q}_1 = -f(r) \beta_{\text{cut}}(T) \kappa_0 T^{5/2} \hat{\mathbf{b}} \hat{\mathbf{b}} \cdot \nabla T$$

$$\mathbf{q}_2 = (1 - f(r)) \frac{k}{(\gamma - 1)} \frac{\rho}{m_p} T \mathbf{v} \hat{\mathbf{b}} \hat{\mathbf{b}}$$



RADIATIVE COOLING

$$H = H^* + \frac{\rho}{4 \lambda_{\perp}} [|z_-| z_+^2 + |z_+| z_-^2]$$

$$\lambda_{\perp} = \lambda_0 \sqrt{\frac{B_w}{|\mathbf{B}|}} |z_{\pm}(r = R_{\odot})| = z_0$$

CORONAL HEATING

ALFVEN WAVES

$$\frac{\partial \epsilon_{\pm}}{\partial t} = -\nabla \cdot (\epsilon_{\pm} [\mathbf{v} \pm \mathbf{v}_A]) - \frac{\epsilon_{\pm}}{2} \nabla \cdot \mathbf{v}$$

$$\frac{\partial \mathbf{v}}{\partial t} = -\mathbf{v} \cdot \nabla \mathbf{v} + \frac{1}{\rho} \left[\frac{1}{c} \mathbf{J} \times \mathbf{B} - \nabla p - \nabla \left(\frac{\epsilon_+ + \epsilon_-}{2} \right) + \rho \mathbf{g} \right] + \frac{1}{\rho} \nabla \cdot (v \rho \nabla \mathbf{v}) + \frac{1}{\rho} \nabla \cdot \left(S \rho \nabla \frac{\partial \mathbf{v}}{\partial t} \right)$$

VISCOSITY

SEMI-IMPLICIT OPERATOR

WAVE TURBULENCE

$$\frac{\partial z_{\pm}}{\partial t} = -(\mathbf{v} \pm \mathbf{v}_A) \cdot \nabla z_{\pm} - \frac{z_{\pm} |z_{\mp}|}{2 \lambda_{\perp}} + \frac{z_{\pm}}{4} (\mathbf{v} \mp \mathbf{v}_A) \cdot \nabla (\ln \rho) + \frac{z_{\mp}}{2} (\mathbf{v} \mp \mathbf{v}_A) \cdot \nabla (\ln |\mathbf{v}_A|)$$

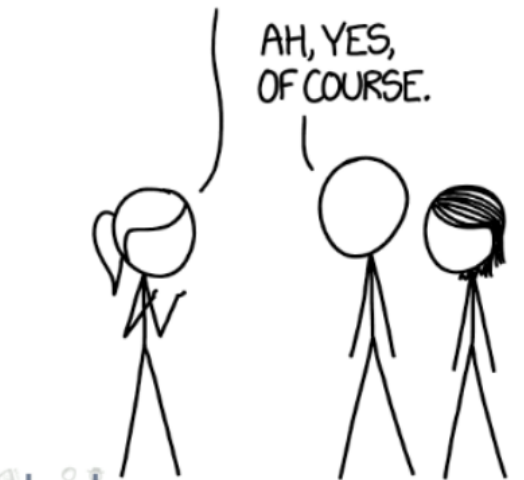
$\nabla \cdot \mathbf{B} = 0$	$p = 2kT\rho/m_p$	$\hat{\mathbf{b}} = \mathbf{B}/ \mathbf{B} $	$\beta_{\infty}(T) = \begin{cases} (T/T_{\infty})^{5/2} & T < T_{\infty} \\ 1 & T \geq T_{\infty} \end{cases}$	$S = (\Delta r^2 \dot{R})^2 + (C_f^2/(1 - C_f)^2 - 1)$
$\mathbf{B} = \nabla \times \mathbf{A}$	$\mathbf{g} = -g_0 R_{\odot}^2 \hat{\mathbf{r}}/r^2$	$\mathbf{v}_A = \mathbf{B}/\sqrt{4\pi\rho}$	$T_{\infty} = 3.5 \times 10^6 \text{ K}$	$C_f = \Delta t \hat{\mathbf{k}} \cdot \mathbf{v}$
$\mathbf{J} = \frac{c}{4\pi} \nabla \times \mathbf{B}$	$\gamma = 5/3$	$B_w = 6.09 \text{ G}$	$f(r) = 1 - 0.5 \tanh((r - 10 R_{\odot})/R_{\odot})$	$C_f^2 = 0.25 \Delta t^2 \dot{R}^2 (v_{\odot}^2 + \mathbf{v}_A ^2)$
		$v_{\odot}^2 = \gamma p/\rho$		$\dot{R}^2 = 4 (\Delta r^{-2} + (r \Delta \theta)^{-2} + (r \Delta \phi \sin \theta)^{-2})$

GPU Implementation:

Caplan et. al. J. of Phys.: Conf. Series. ASTRONOM 2018. 1225,1 (2019) 012012

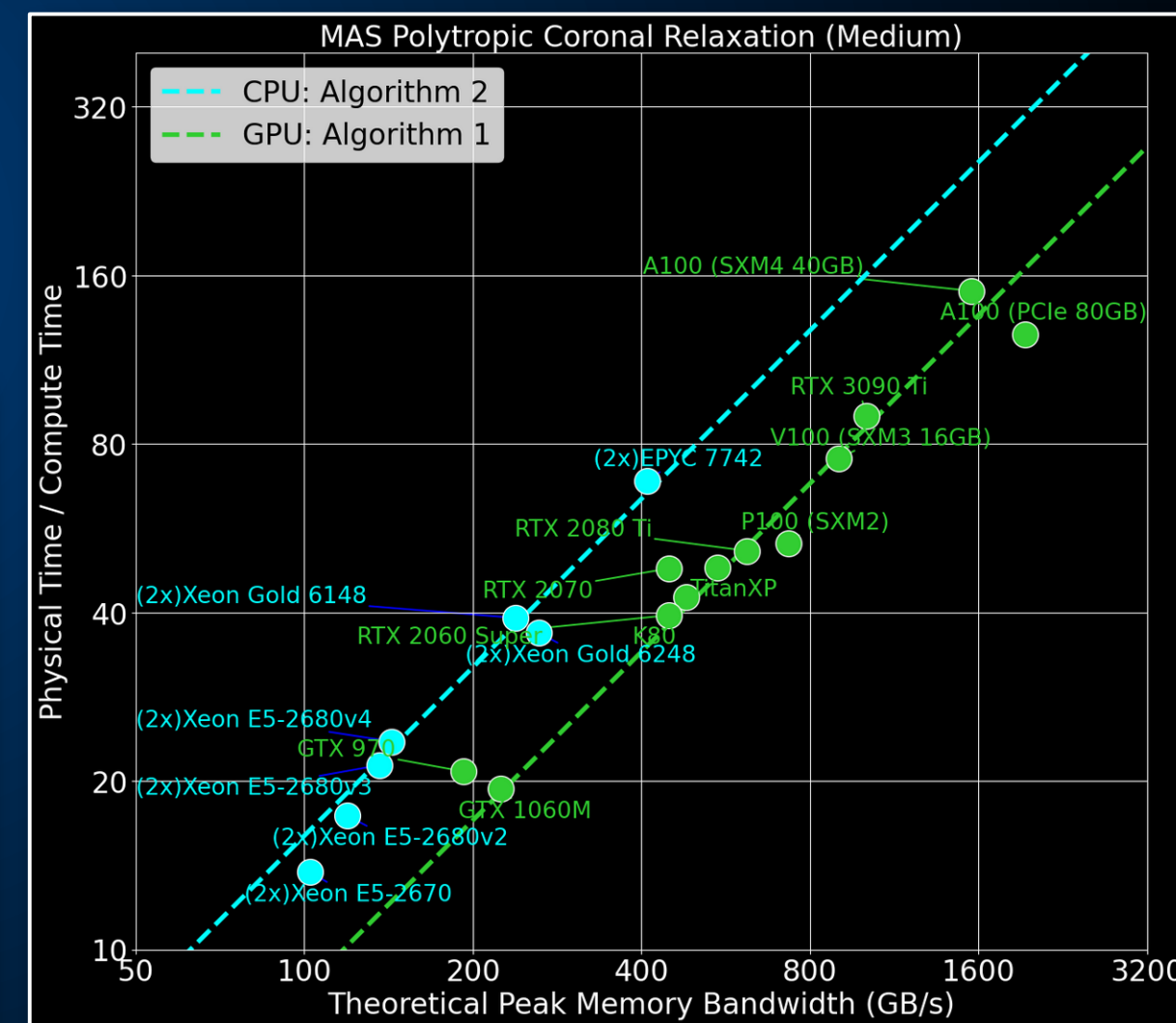
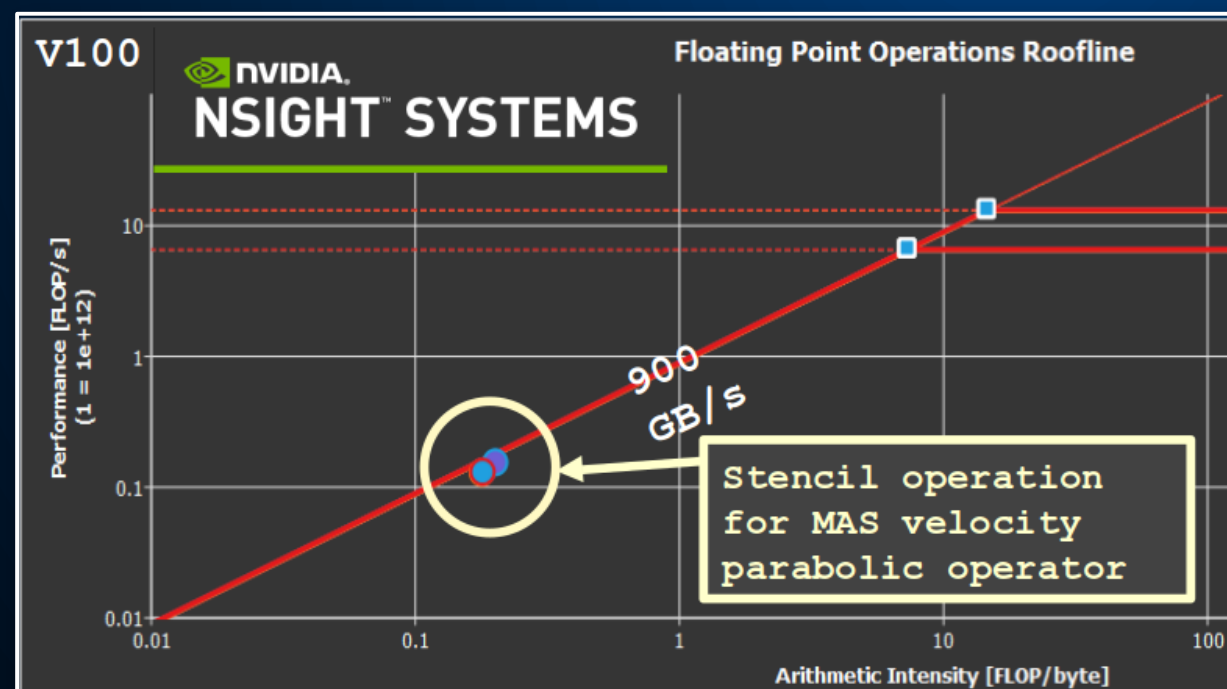
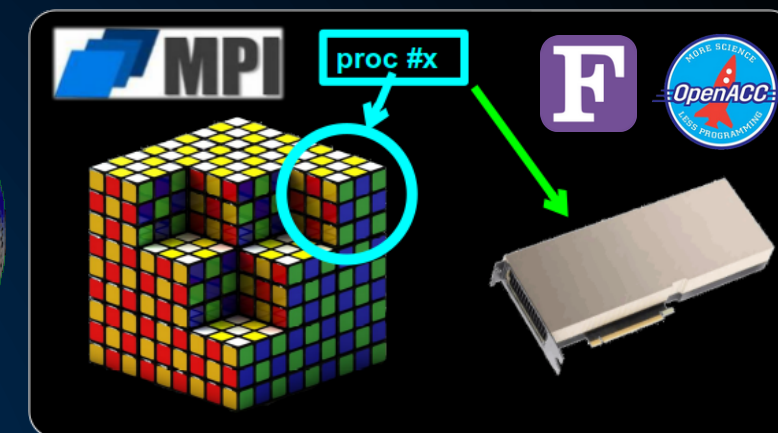
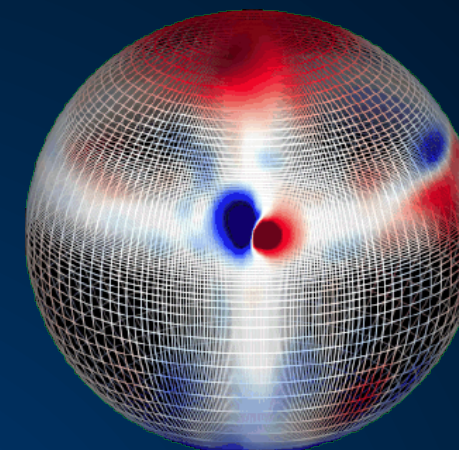
Caplan et. al. IEEE IPDPSW Proceedings., (2023) 582-590.

THE SUN'S ATMOSPHERE IS A SUPERHOT PLASMA GOVERNED BY MAGNETOHYDRODYNAMIC FORCES...

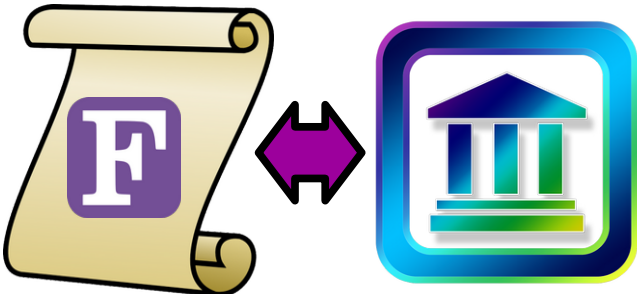


WHENEVER I HEAR THE WORD "MAGNETOHYDRODYNAMIC" MY BRAIN JUST REPLACES IT WITH "MAGIC."

- Finite difference on a logically rectangular non-uniform spherical grid
- Preconditioned (PC) Conjugate Gradient solvers with two PCs, **PC1**: GPU & CPU, and **PC2** (better!): CPU-Only (for now)
- Fortran**, parallelized with **MPI**, later GPU-accelerated with **MPI+OpenACC**
- Highly memory bandwidth bound! (low AI)



Libraries



cuSPARSE

Standard Language



Directive APIs



OpenMP
OpenACC
More Science, Less Programming

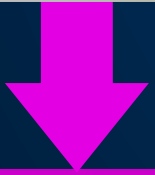
Low-Level APIs



CUDA FORTRAN
cass-support/
cfortran
OpenCL

Programmer Productivity

Programmer Control



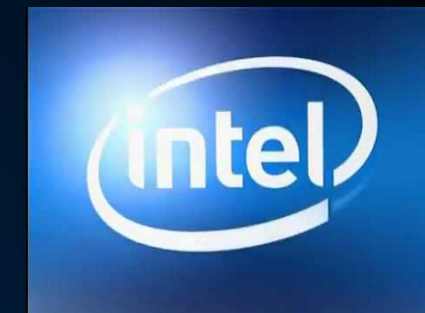
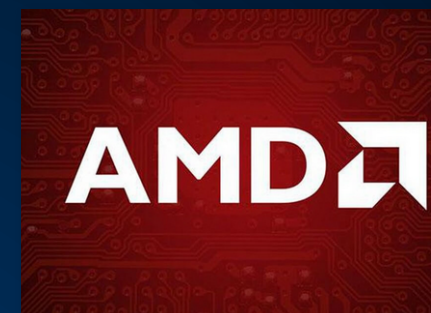
```
do concurrent (i=1:N, j=1:M)
  Computation
enddo
```

- ⊘ Introduced in ISO Standard Fortran 2008
- ⊘ Indicates loop can be run with **out-of-order** execution
- ⊘ Can be hint to the compiler that loop **may** be parallelizable

- ⊘ No current support for atomics, device selection, conditionals, etc.
- ⊘ Fortran 2023 specification added reductions

Compatibility Matrix

[A. Herten] github.com/AndiH/gpu-lang-compat



DC

	 (HPE)	 (Early)
	 (GCC/HPE)	 (Converter*)

OpenACC

More Science, Less Programming



The OpenMP name and the OpenMP logo are registered trademarks of the OpenMP Architecture Review Board

*github.com/intel/intel-application-migration-tool-for-openacc-to-openmp

Flang?

Why use Fortran standard parallelism?

- Ⓧ Longevity (ISO)
- Ⓧ Smaller code footprint
- Ⓧ More familiar to domain scientists
- Ⓧ Parallelism on CPUs too!
- Ⓧ Currently less portable than directives (may change)



These also apply to legacy codes!

Original Non-Parallelized Code

```
do k=1,np
  do j=1,nt
    do i=1,nrm1
      br(i,j,k) = (phi(i+1,j,k)-phi(i,j,k))*dr_i(i)
    enddo
  enddo
enddo
```

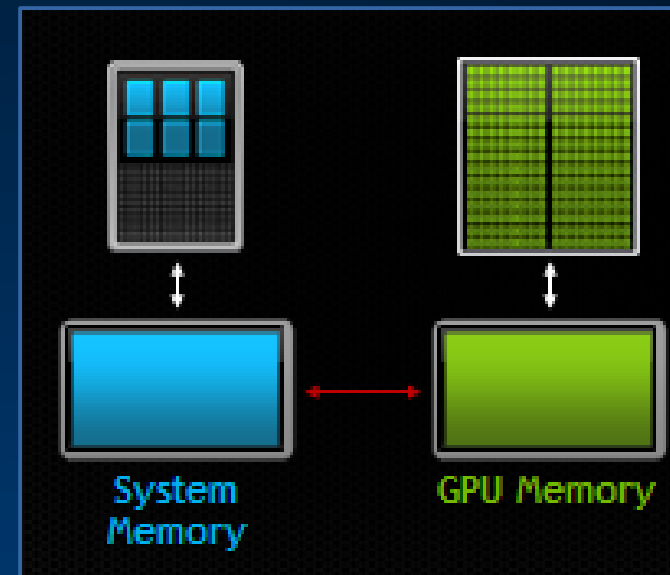
OpenACC Parallelized Code

```
!$acc enter data copyin(phi,dr_i)
!$acc enter data create(br)
!$acc parallel loop default(present) collapse(3) async(1)
do k=1,np
  do j=1,nt
    do i=1,nrm1
      br(i,j,k) = (phi(i+1,j,k)-phi(i,j,k))*dr_i(i)
    enddo
  enddo
enddo
!$acc wait
!$acc exit data delete(phi,dr_i,br)
```

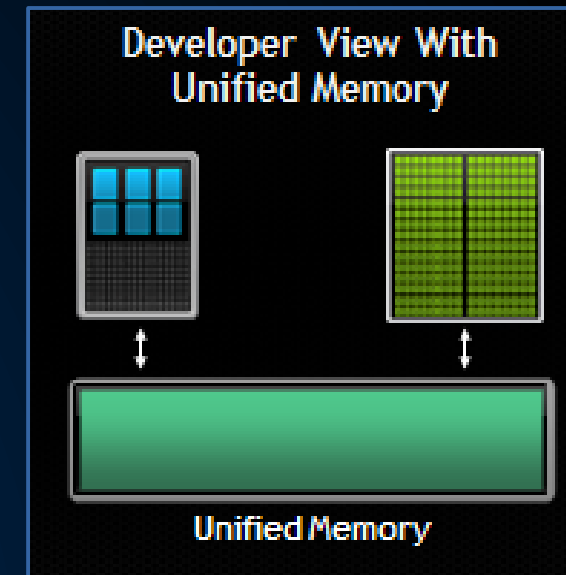
Fortran Standard Parallelized Code

```
do concurrent (k=1:np,j=1:nt,i=1:nrm1)
  br(i,j,k) = (phi(i+1,j,k)-phi(i,j,k))*dr_i(i)
enddo
```


- ⊖ CPU and GPU have separate memories
- ⊖ Transfer between memories is slow, so want to keep data on GPU
- ⊖ OpenMP/ACC have explicit data movement directives
- ⊖ Unified memory (UM) auto pages data so can make DC efficient without data directives
- ⊖ **Grace-Hopper has fast CPU - GPU memory sharing, so it can perform as well with UM as manual data management!**



VS



```
!$acc enter data copyin(x)      -gpu=managed
!$acc exit data copyout(x)     -gpu=unified
```

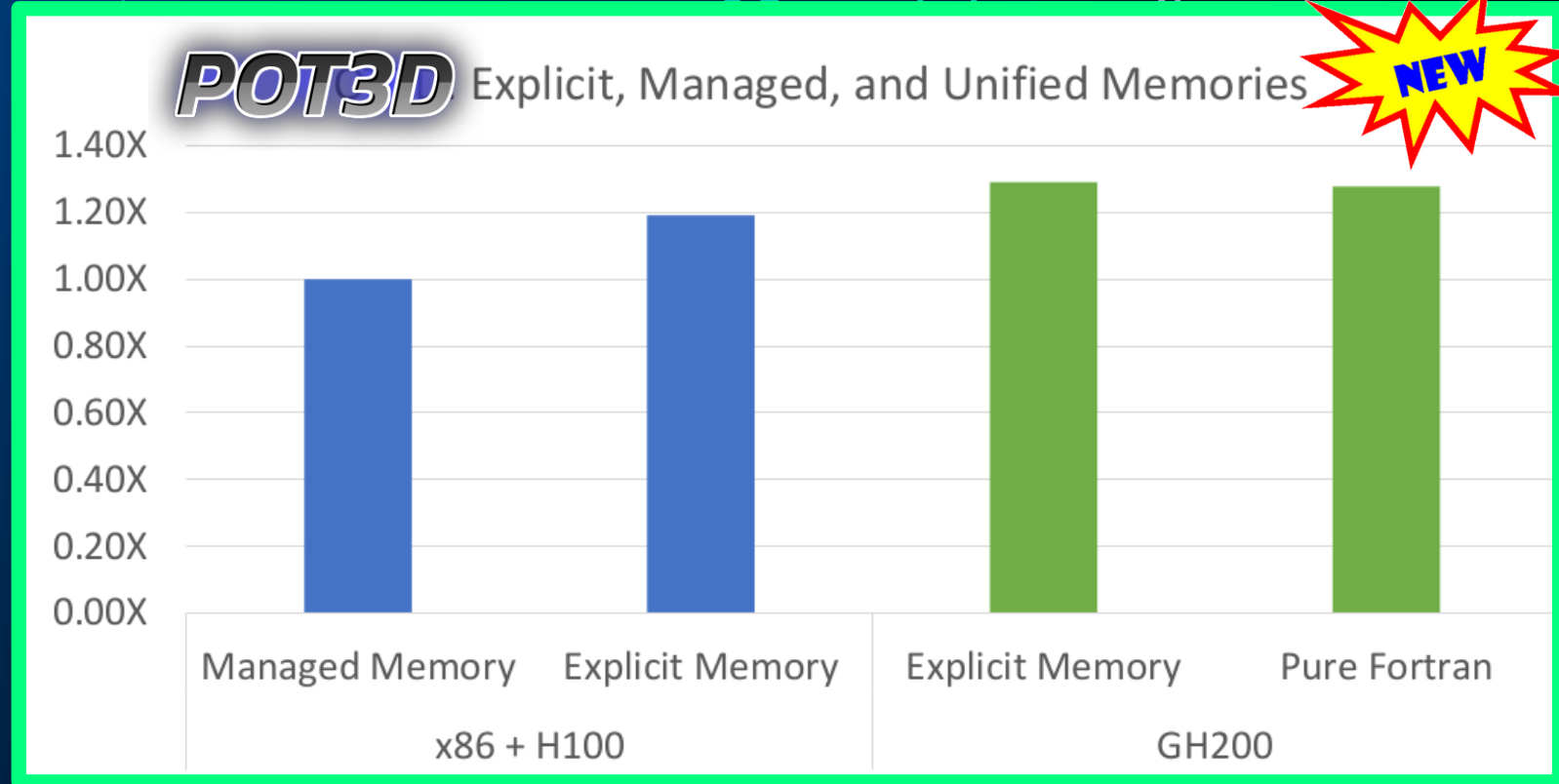
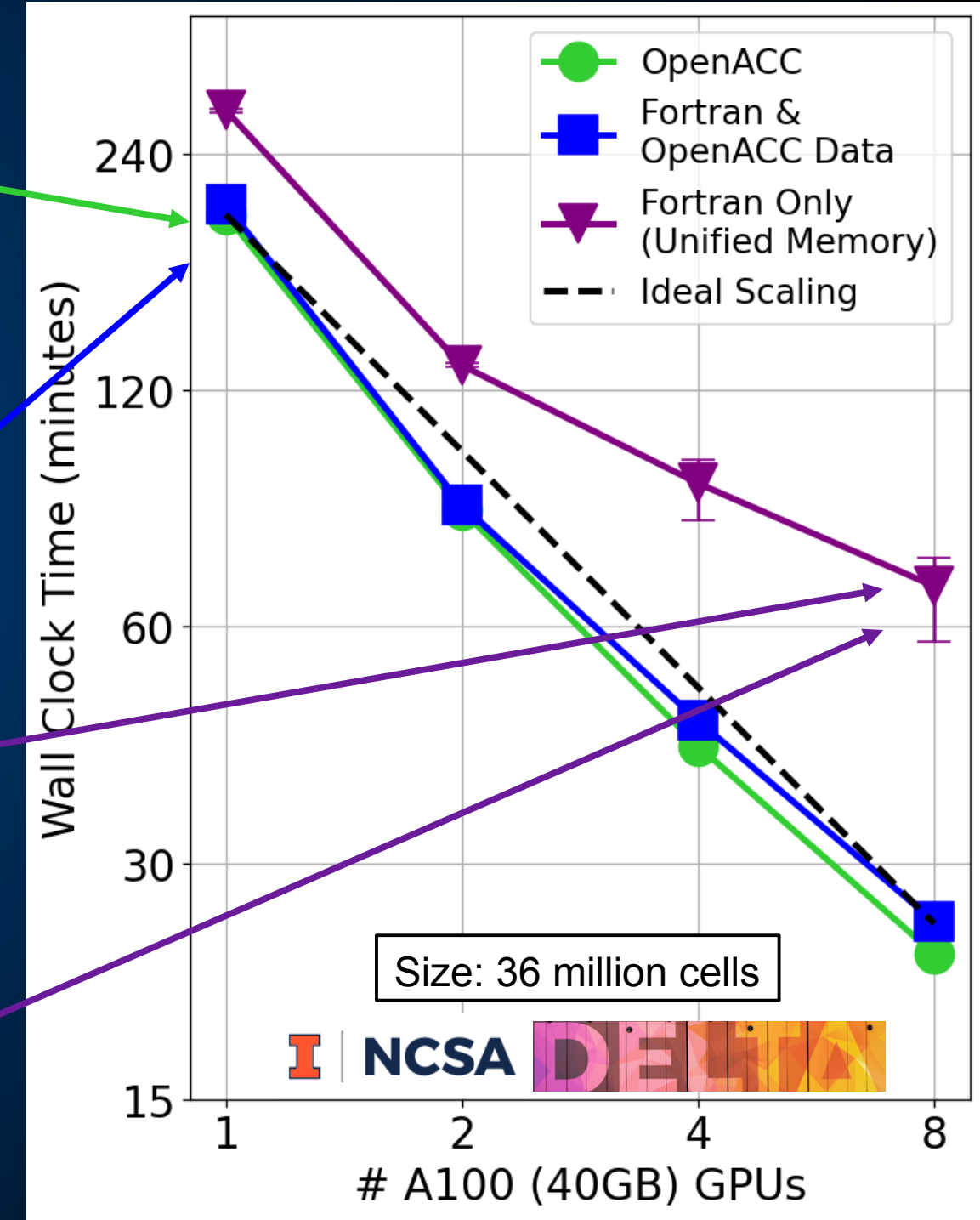
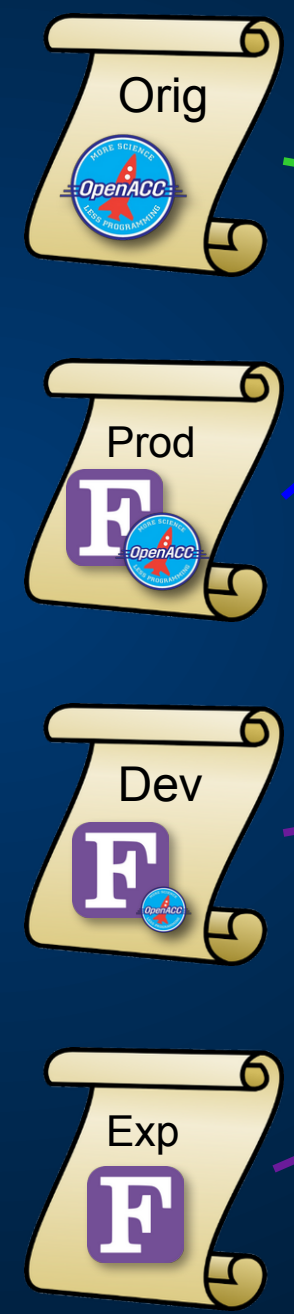


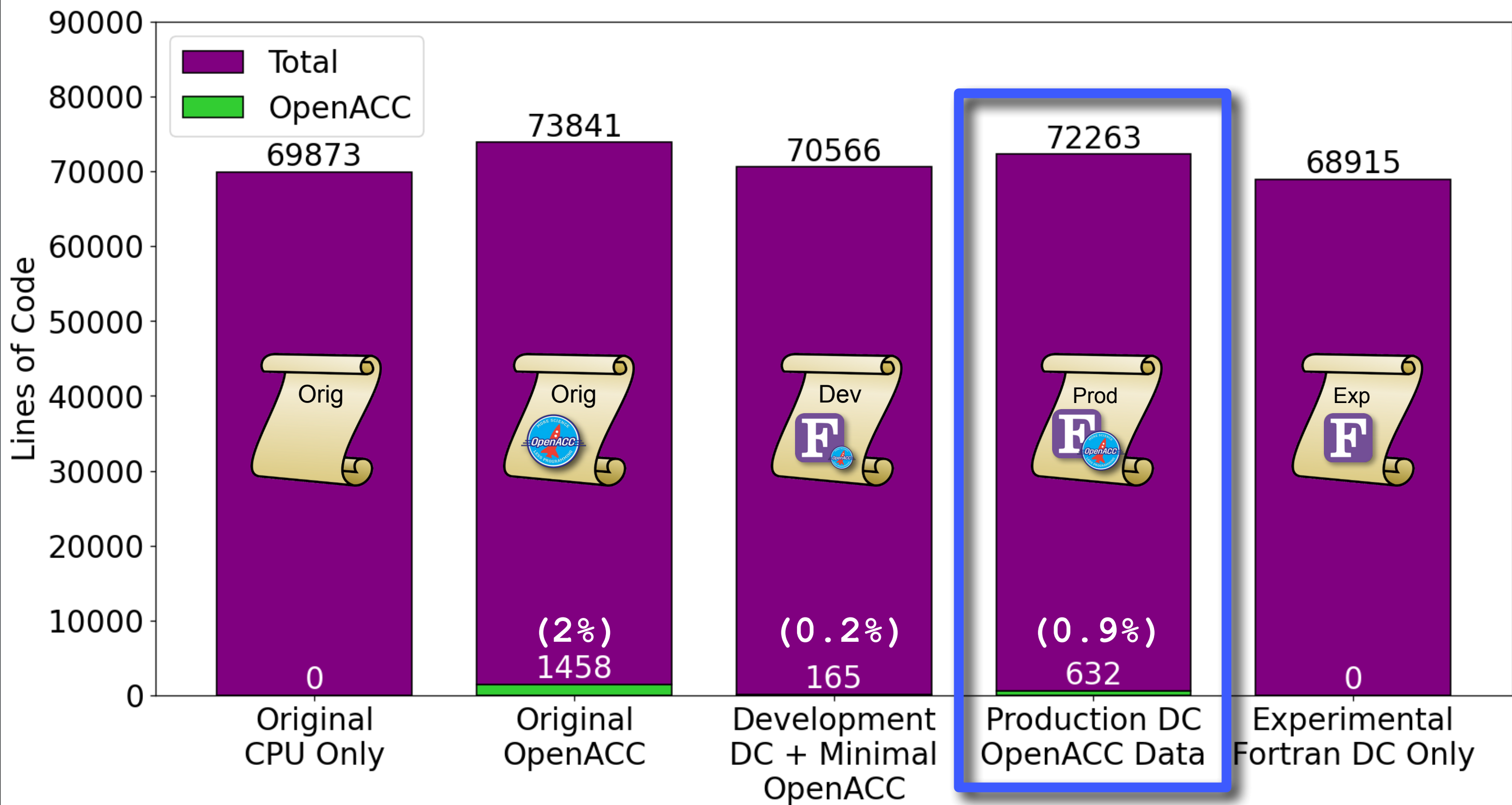
Figure courtesy of Jeff Larkin, NVIDIA

Caplan et. al., 13th AsHES Workshop, IEEE IPDPSW Proceedings., (2023) 582-590

- ⊖ Replaced OpenACC loops with DC
- ⊖ Left OpenACC for reductions (DC “reduce” too new!), and for minimal needs (routine, device selection, etc.)
- ⊖ Two branches:
 - Development: Minimal OpenACC
 - Production: Development with OpenACC added for data movement
- ⊖ Experimental version with ZERO directives
- ⊖ Performance of Production branch similar to original OpenACC implementation
- ⊖ Performance of Development and Experimental branch slower due to non-optimal UM with MPI (should get better with updates (e.g. GH))



Fortran on GPUs: MAS Implementation



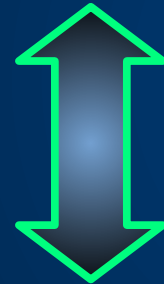
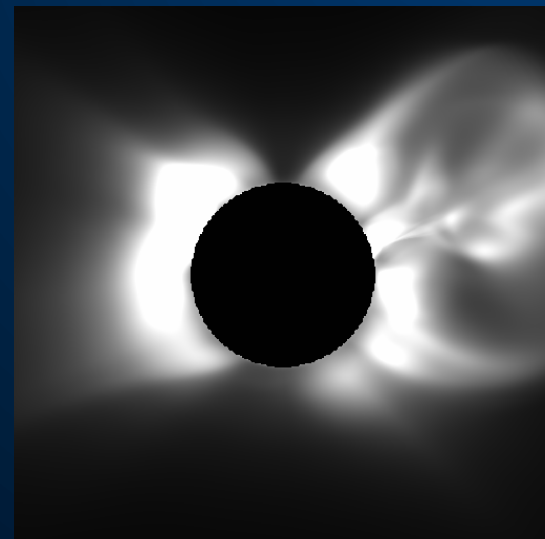
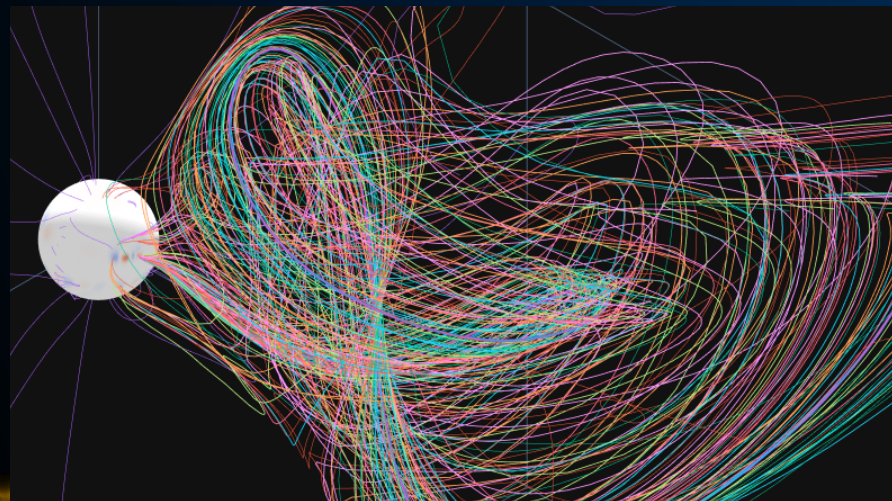
☉ Real case: Solar storm on 3/28/2022:

A Cannibal CME is Approaching Earth
 MARCH 30, 2022 / DR.TONY PHILLIPS
 March 29, 2022: On March 28th, sunspot AR2975 unleashed a frenzy of solar flares—more than 17 in all. There were 11 C-class flares and 6 M-flares. At least two full-halo CMEs emerged from the chaos:



CORHEL-CME

☉ Simulated CME:



☉ Computational Environment:

DELTA | **NCSA**

NCSA Delta 8xGPU Node

# CPUs x Model	(2x) EPYC 7742
# GPUs x Model	8x A100-40GB SXM4
Peak DP FLOP/s / GPU	9.8 TFLOP/s
Memory / GPU	40 GB
Memory Bandwidth/GPU	1555 GB/s

A100 40GB SXM4

nvhpc 24.1 OpenMPI 4
gfortran 10.2 OpenMPI 4



EXPANSE | **SDSC**
 COMPUTING WITHOUT BOUNDARIES

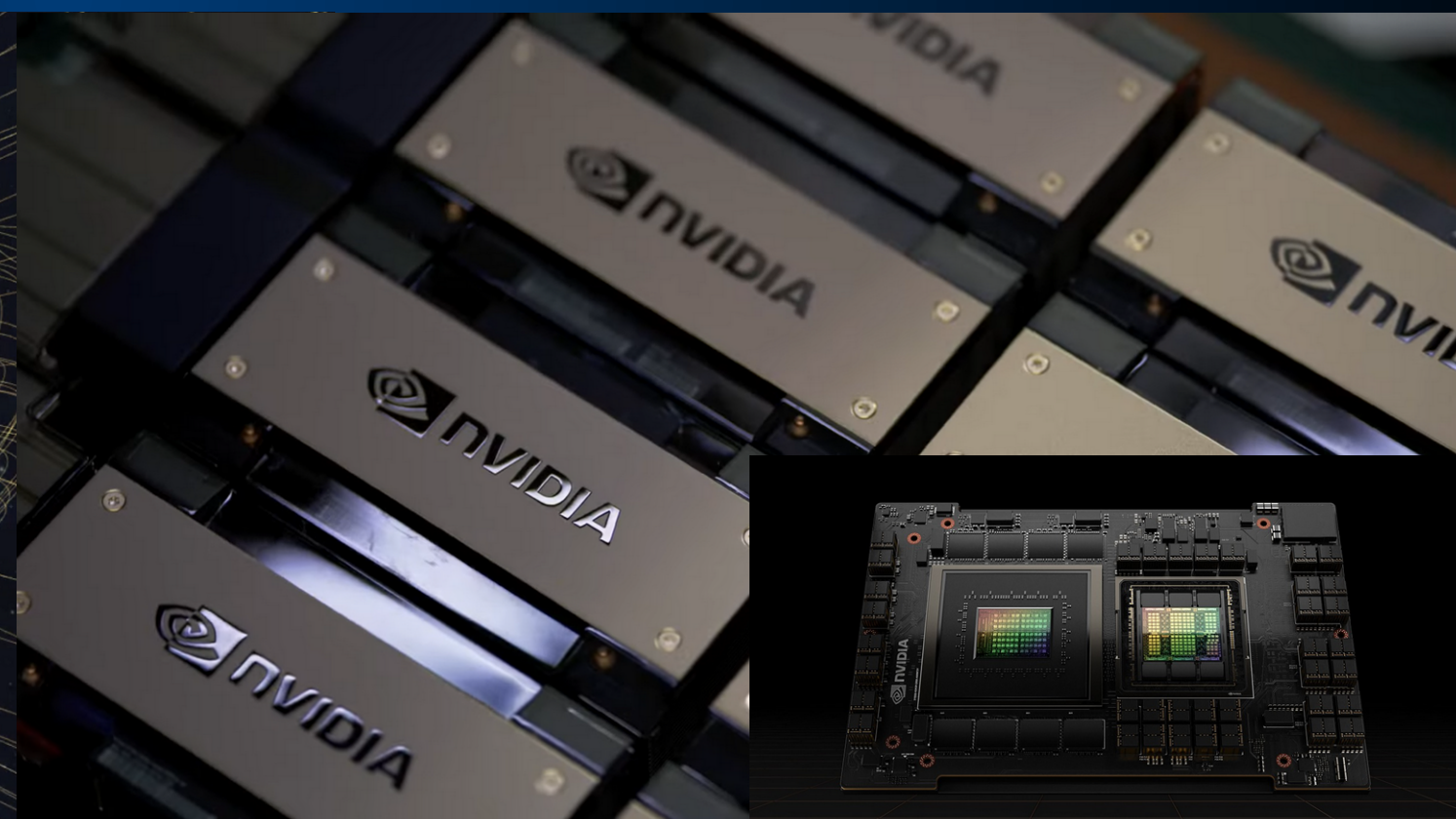
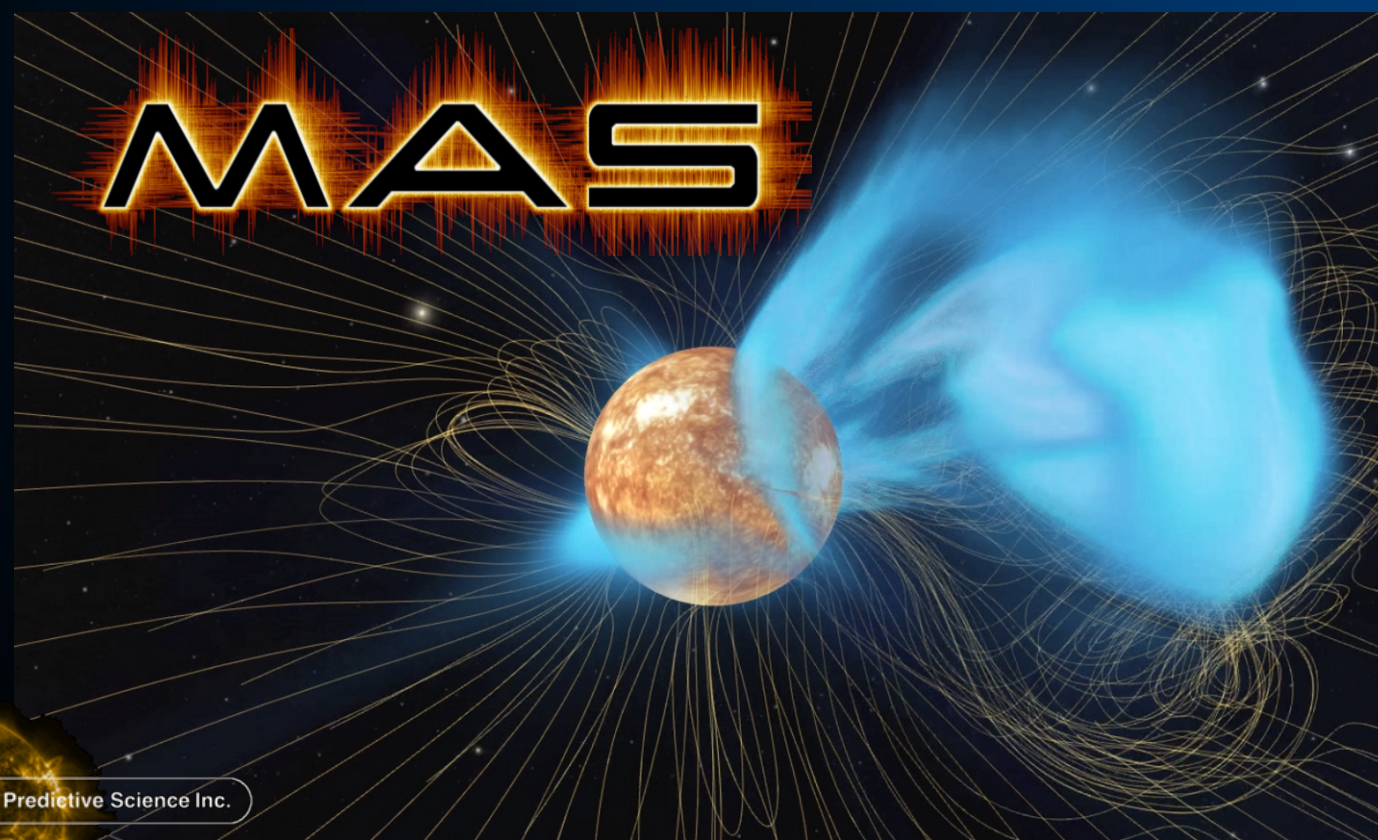
# CPUs x Model	(2x) EPYC 7742
# Total Cores	128 (we use 64)
Peak FLOP/s	7.0 TFLOP/s
Memory	256 GB
Total Memory Bandwidth	381.4 GB/s

- Full design and simulation of the CME uses six runs of MAS, each with various grid sizes and run times:

CORHEL-CME: CME 3/28/2022 Run Type	Size (Millions of Cells)	CPU Expanse 2xEPYC7742 4 Nodes [1.6 TB/s MMB]		GPU AWS P3 8xV100 1 Node [7.2 TB/s MMB]		GPU Delta 8xA100 (40GB) 1 Node [12.4 TB/s MMB]	
		Computation	Processing	Computation	Processing	Computation	Processing
Flux Rope Eruption (ZBMHD)	8.3	0.5	0.01	0.4	0.01	0.2	0.01
Background Relaxation Corona (TMHD)	3.1	2.1		4.1		3	
Background Relaxation Heliosphere (PMHD+2D)	32.7	1.1	0.6	1.1	0.6	0.8	0.6
CME Eruption (TMHD)	29.6	7.6		3.7		2.4	
CME Coronal Propagation (TMHD)	9.3	25.2	1	22.1	1	14.8	1
CME Heliosphere Propagation (PMHD+2D)	32.7	4.4		1.2		0.8	
<i>Total</i>		40.9	1.7	32.6	1.7	22	1.7
Total Wall Clock:		42.6 Hours		34.3 Hours		23.7 Hours	



The MAS code, GPU-accelerated with Fortran standard parallelism (do concurrent) and minimal OpenACC data movement directives, allows us to achieve a one day turn-around for realistic CME simulations on a single multi-GPU compute node

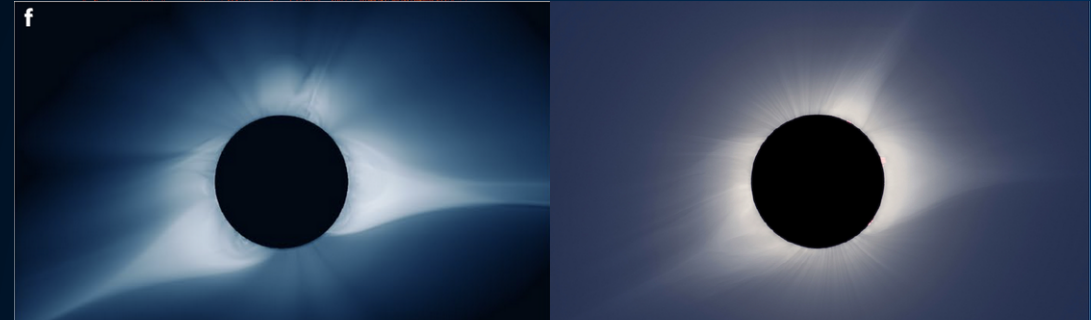


Coming Soon! Total Solar Eclipse

PSI has a tradition to use our MAS MHD model to predict the appearance of upcoming total solar eclipses:

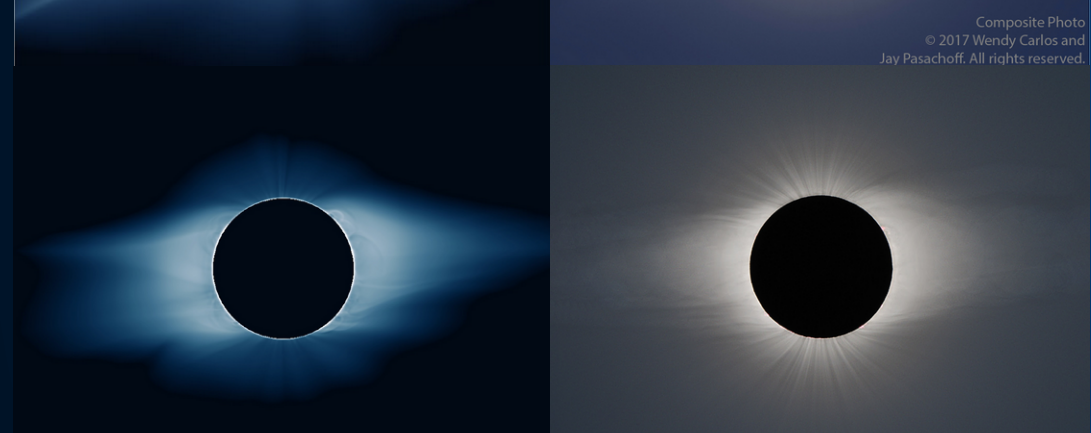
MAS Observation

2017



Composite Photo © 2017 Wendy Carlos and Jay Pasachoff. All rights reserved.

2019



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2021



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April 8, 2024, Solar Eclipse

On April 8, 2024, a total solar eclipse will cross North America, passing over Mexico, United States, and Canada.

