

# **An Open Source High-Performance** Flux Transport Model

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# Overview

- Surface flux transport models
- Open Source Flux Transport (OFT)
- High Performance Flux Transport (HipFT)
- Flow and diffusion models
- Data Assimilation
- Multiple Realizations
- Numerical Methods
- Code Implementation
- → Examples
- Availability



## Surface Flux Transport Models

- SFT treats the solar surface radial magnetic field as a scalar quantity subject to 2D surface flows and processes
- Used to generate full-Sun maps, constrain dynamo models, study surface dynamics, solar cycle prediction, etc.
- Many models exist: ADAPT, LMSAL-ESFAM, AFT, etc.
- While some produce publicly available full-Sun maps, none are currently open-source or able to be run on-demand



The Open Source Flux Transport Model (OFT)

- Part of the "Improving Space Weather Predictions with Data-Driven Models of the Solar Atmosphere and Inner Heliosphere" SWQU project
- Open source and extensible Three main components:

OFTpy: ConFlow:

HipFT:

Aquire and prepare observational data Generate supergranular convective flows Integrate the flux transport model



# High Performance Flux Transport Model (HipFT)

Implements advection, diffusion, data assimilation, and flux emergence over multiple realizations using high-accuracy numerical methods and CPU/GPU parallelism

$$\frac{\partial B_r}{\partial t} = -\nabla_s \cdot \left( B_r \, \mathbf{v} \right) + \nabla_s \cdot \left( \nu \, \nabla_s \, B_r \right) \cdot$$

$$\nabla_s \cdot (B_r \mathbf{v}) = \frac{1}{R_{\odot} \sin \theta} \frac{\partial}{\partial \theta} (\sin \theta B_r v_{\theta}) + \frac{1}{R_{\odot} \sin \theta} \frac{\partial}{\partial \phi} (B_r v_{\theta})$$

$$\nabla_s \cdot (\nu \, \nabla_s \, B_r) = \frac{1}{R_{\odot}^2 \, \sin \theta} \frac{\partial}{\partial \theta} \left( \nu(\theta, \phi, B_r) \, \sin \theta \, \frac{\partial B_r}{\partial \theta} \right) + \frac{1}{R_{\odot}^2 \, \sin^2 \theta} \, \frac{\partial}{\partial \phi} \left( \nu(\theta, \phi, B_r) \, \frac{\partial B_r}{\partial \theta} \right) + \frac{1}{R_{\odot}^2 \, \sin^2 \theta} \, \frac{\partial}{\partial \phi} \left( \nu(\theta, \phi, B_r) \, \frac{\partial B_r}{\partial \theta} \right) + \frac{1}{R_{\odot}^2 \, \sin^2 \theta} \, \frac{\partial}{\partial \phi} \left( \nu(\theta, \phi, B_r) \, \frac{\partial B_r}{\partial \theta} \right) + \frac{1}{R_{\odot}^2 \, \sin^2 \theta} \, \frac{\partial}{\partial \phi} \left( \nu(\theta, \phi, B_r) \, \frac{\partial B_r}{\partial \theta} \right) + \frac{1}{R_{\odot}^2 \, \sin^2 \theta} \, \frac{\partial}{\partial \phi} \left( \nu(\theta, \phi, B_r) \, \frac{\partial}{\partial \theta} \right) + \frac{1}{R_{\odot}^2 \, \sin^2 \theta} \, \frac{\partial}{\partial \phi} \left( \nu(\theta, \phi, B_r) \, \frac{\partial}{\partial \theta} \right) + \frac{1}{R_{\odot}^2 \, \sin^2 \theta} \, \frac{\partial}{\partial \phi} \left( \nu(\theta, \phi, B_r) \, \frac{\partial}{\partial \theta} \right) + \frac{1}{R_{\odot}^2 \, \sin^2 \theta} \, \frac{\partial}{\partial \phi} \left( \nu(\theta, \phi, B_r) \, \frac{\partial}{\partial \theta} \right) + \frac{1}{R_{\odot}^2 \, \sin^2 \theta} \, \frac{\partial}{\partial \phi} \left( \nu(\theta, \phi, B_r) \, \frac{\partial}{\partial \theta} \right) + \frac{1}{R_{\odot}^2 \, \sin^2 \theta} \, \frac{\partial}{\partial \phi} \left( \nu(\theta, \phi, B_r) \, \frac{\partial}{\partial \theta} \right) + \frac{1}{R_{\odot}^2 \, \sin^2 \theta} \, \frac{\partial}{\partial \phi} \left( \nu(\theta, \phi, B_r) \, \frac{\partial}{\partial \theta} \right) + \frac{1}{R_{\odot}^2 \, \sin^2 \theta} \, \frac{\partial}{\partial \phi} \left( \nu(\theta, \phi, B_r) \, \frac{\partial}{\partial \theta} \right) + \frac{1}{R_{\odot}^2 \, \sin^2 \theta} \, \frac{\partial}{\partial \phi} \left( \nu(\theta, \phi, B_r) \, \frac{\partial}{\partial \theta} \right) + \frac{1}{R_{\odot}^2 \, \sin^2 \theta} \, \frac{\partial}{\partial \phi} \left( \nu(\theta, \phi, B_r) \, \frac{\partial}{\partial \theta} \right) + \frac{1}{R_{\odot}^2 \, \sin^2 \theta} \, \frac{\partial}{\partial \phi} \left( \nu(\theta, \phi, B_r) \, \frac{\partial}{\partial \phi} \right) + \frac{1}{R_{\odot}^2 \, \sin^2 \theta} \, \frac{\partial}{\partial \phi} \left( \nu(\theta, \phi, B_r) \, \frac{\partial}{\partial \phi} \right) + \frac{1}{R_{\odot}^2 \, \sin^2 \theta} \, \frac{\partial}{\partial \phi} \left( \nu(\theta, \phi, B_r) \, \frac{\partial}{\partial \phi} \right) + \frac{1}{R_{\odot}^2 \, \sin^2 \theta} \, \frac{\partial}{\partial \phi} \left( \nu(\theta, \phi, B_r) \, \frac{\partial}{\partial \phi} \right) + \frac{1}{R_{\odot}^2 \, \sin^2 \theta} \, \frac{\partial}{\partial \phi} \left( \nu(\theta, \phi, B_r) \, \frac{\partial}{\partial \phi} \right) + \frac{1}{R_{\odot}^2 \, \sin^2 \theta} \, \frac{\partial}{\partial \phi} \left( \nu(\theta, \phi, B_r) \, \frac{\partial}{\partial \phi} \right) + \frac{1}{R_{\odot}^2 \, \cos^2 \theta} \, \frac{\partial}{\partial \phi} \left( \nu(\theta, \phi, B_r) \, \frac{\partial}{\partial \phi} \right) + \frac{1}{R_{\odot}^2 \, \cos^2 \theta} \, \frac{\partial}{\partial \phi} \left( \nu(\theta, \Phi, B_r) \, \frac{\partial}{\partial \phi} \right) + \frac{1}{R_{\odot}^2 \, \cos^2 \theta} \, \frac{\partial}{\partial \phi} \left( \nu(\theta, \Phi, B_r) \, \frac{\partial}{\partial \phi} \right) + \frac{1}{R_{\odot}^2 \, \cos^2 \theta} \, \frac{\partial}{\partial \phi} \left( \nu(\theta, \Phi, B_r) \, \frac{\partial}{\partial \phi} \right) + \frac{1}{R_{\odot}^2 \, \cos^2 \theta} \, \frac{\partial}{\partial \phi} \left( \nu(\theta, \Phi, B_r) \, \frac{\partial}{\partial \phi} \right) + \frac{1}{R_{\odot}^2 \, \cos^2 \theta} \, \frac{\partial}{\partial \phi} \left( \nu(\theta, \Phi, B_r) \, \frac{\partial}{\partial \phi} \right) + \frac{1}{R_{\odot}^2 \, \cos^2 \theta} \, \frac{\partial}{\partial \phi} \left( \nu(\theta, \Phi, B_r) \, \frac{\partial}{\partial \phi} \right) + \frac{1}{R_{\odot}^2 \, \cos^2 \theta} \, \frac{\partial}{\partial \phi} \left( \nu(\theta, \Phi, B_r) \, \frac{\partial}{\partial \phi} \right) + \frac{1}{R_{\odot}^2 \, \cos^2 \theta} \, \frac{\partial}{\partial \phi} \right) + \frac{1}{R_{\odot}^2 \, \frac$$

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 $\partial B_r$ 

# **HipFT Flow Models**

Differential rotation

$$v_{\phi}(\theta) = \left[d_0 + d_2 \cos^2(\theta) + d_4 \cos^4(\theta)\right] \sin \theta,$$

# Meridianal flows

$$v_{\theta}(\theta) = -\left[m_1 \cos \theta + m_3 \cos^3 \theta + m_5 \cos^5 \theta\right] \sin \theta$$

# Velocity attenuation

$$v_{\theta/\phi} \to v_{\theta/\phi} \left[ 1.0 - \tanh\left(\frac{|B_r|}{B_0}\right) \right],$$

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90

60

30

0

-30

-60

Latitude (degrees)



# **HipFT Flow Models**

- Diffusion in SFT models used as a proxy for the flux cancellation caused by granular and super-granular motions
- However, there are advantages to directly modeling these flows
- The default HipFT resolution of 1024x512 is high enough to resolve most of the super-granular scale sizes
  - ConFlow generates a sequence of flow data encompassing random motions and super-granulation
  - HipFT reads in the files and drives the FT with the flows
  - Some diffusion is still necessary to represent flux cancellation at smaller scales





ConFlow





# **HipFT Diffusion Models**

- Diffusion coefficient can be constant, or a user-defined spatially varying file
- HipFT can be used as a magnetogram smoother, in which case one can select a grid-based diffusion coefficient







 $\nu(\theta,\phi)$ 

# $\nu_q = \alpha_{\nu} \left[ (\Delta \theta)^2 + (\Delta \phi \sin \theta)^2 \right],$



**DISK LOS DATA** 









Acquire data (e.g. HMI M720s LOS through JSOC drms py package)

Convert line-of-sight field into radial field:  $B_r = B_{\rm los}/\mu$ 

Map to Carrington frame with resolution 10240 x 5120 to avoid under-sampling

Reduce size with fluxpreserving integral binning:



- Set quality weights:  $\mu = \cos \theta_d \in [0, 1]$
- $\theta_d$  is the center to limb angle

Use weights with power and cutoff parameters to assimilate data into HipFT:  $= \mu^{\alpha_{\mu}}$  $\mu < \mu_{\rm lim}$ 0.W.  $(F B_{r:d} - F B_r)$ 

# **Data Assimilation**

 Data assimilation uses the output data from **OFT**py

# A default weighting function is included in the data cube, applied as:

$$B_r \to F B_{r;d} + (1 - F)$$

 The center-to-limb distance is also provided, which can be used to generate a user-defined custom weight profile:

 $F = \mu^{\alpha_{\mu}}$ 

 $\mu < \mu_{\lim} \& |\theta_1| < \theta_{1,\lim},$ 

 $B_r$ .

F = 0 o.w.,

# **Multiple Realizations**

- Can run multiple realizations simultaneously across many model parameters
- Current cross-realization parameters include diffusion rate, flow profile coefficients, flow attenuation levels, and data assimilation options
- Post processing python scripts are included to analyze results







# **HipFT Numerical Methods**

# Non-uniform, logically-rectangular spherical surface staggered grid



•	Br
$\diamond$	Vθ
	Vφ

# **HipFT Numerical Methods**



ADVECTION: 3<sup>rd</sup>-order SSPRK(4,3) DIFFUSION: 2<sup>nd</sup>-order Runge-Kutta-Gegenbauer Super Time-Stepping

**ADVECTION:** 3<sup>rd</sup>-order WENO3 **DIFFUSION:** 2<sup>nd</sup>-order Central Finite Difference

# Validation:

 $v_{\phi} = \Omega \, \sin \theta$ 

 $\Omega = 1.8076...\,\mathrm{km/s}$ 

 $\nu = 500 \,\mathrm{km}^2/\mathrm{s}$ 

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$$u(\theta,\phi,t) = 1000 e^{-42\nu t} \left( Y_6^0(\theta,\phi) + \sqrt{\frac{14}{11}} Y_6^5(\theta,\phi) \right)$$

$$\Delta\theta, \Delta\phi=\pi/16$$



 $\Delta \theta, \Delta \phi = \pi/32$ 







 $\Delta\theta, \Delta\phi = \pi/128$ 



# **HipFT Code Implementation**

- Written in Fortran 2023
- Parallelized for multi-core CPU and GPUs with Fortran standard's `do concurrent` and **OpenMP** Target for CPU-GPU data movement

do concurrent (i=1:N,j=1:M) Computation enddo

!\$omp target enter data map(to:a) !\$omp target enter data map(alloc:b)

Computation

- !\$omp target exit data map(from:a)
- !\$omp target exit data map(release:b)
- Parallelized for multiple multi-CPU/GPU nodes across realizations with MPI







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# result) 1 i ana ita i ortran



## **HipFT Code Performance**



**Test:** 28-day run at 1024x512 with analytic flow models and diffusion. Eight realizations spanning various levels of diffusion and flow attenuation



# **OFT Example Production Run**

Initial map from AFT model, HMI data assimilation (1-hour cadence), ConFlow (1CR) and analytic flows with 500G attenuation, diffusion of 175 km<sup>2</sup>/s

# Runtime on an NVIDIA RTX 2080Ti GPU:



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### Butterfly Diagram (1CR average)



# Comparison of OFT to other SFT models

- Maps from FT models are processed by interpolating to 300x150 resolution, flux balancing, and smoothing
- Note some models apply scaling factors to the HMI data 2014-06-14 23:59:52 2014-06-15 08:00:00



## **HipFT Availability**



# **HipFT Installation**

## > git clone https://github.com/predsci/HipFT.git

### > cd HipFT

### > cp build examples/build <CLOSEST>.sh build local.sh

### Edit build local.sh to reflect local system/compiler

### > ./build local.sh

### > cd testsuite; ./run test suite.sh

Data set for production level example run:

# https://zenodo.org/records/10271121



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# GitHub



# Full description of OFT (and HipFT) will be given in a series of papers (in preparation)

More features being added to HipFT:
→ Random flux emergence, source terms
→ Quality of life updates + processing

